#### Chapter II

DEFINITIONS AND SOME PROPERTIES OF STEINER TRIPLE SYSTEMS

#### 2.0 Introduction

In this chapter Steiner triple systems and related concepts are introduced. A few examples of Steiner triple systems are also provided. Elementary properties concerning the structure of Steiner triple systems are derived for later uses.

### 2.1 Definitions and Examples

By a <u>p-subset</u> of a set  $\Lambda$  we mean any subset of  $\Lambda$  that contains exactly p elements.

2.1.1 <u>Definition</u>. A <u>Steiner triple system</u>, abbreviated as STS, is an ordered pair (A,S(A)), where A is a non-empty finite set, S(A) is a family of 3-subsets of A such that for any pair of distinct elements a,b in A there exists a unique element c in A such that  $\{a, b, c\} \in S(A)$ .

Any element of S(A) will be called a <u>triple</u> of (A,S(A)) and any 3-subset of A which is not in S(A) will be called a <u>triangle</u> of (A,S(A)). If A contains n element we say that (A,S(A)) is a STS of <u>order</u> n.

The followings are examples of STS of orders 1,3,7,

Example (i). Let 
$$A = \{1\}$$
,  $S(A) = \emptyset$ .  
Example (ii). Let  $A = \{1, 2, 3\}$ ,  $S(A) = \{\{1, 2, 3\}\}$ .

Example (iii). Let  $A = \{1, 2, ..., 7\}$  and S(A) consists of the following 3-subsets of A:

$$\{1,2,3\}$$
  $\{2,4,6\}$   $\{3,4,7\}$   $\{1,4,5\}$   $\{2,5,7\}$   $\{3,5,6\}$   $\{1,6,7\}$ 

2.1.2 <u>Definition</u>. By a <u>subsystem</u> of a STS (A,S(A)) we mean any STS (B,S(B)) such that  $B \subseteq A$  and  $S(B) \subseteq S(A)$ .

The condition  $S(B) \subset S(A)$  implies that  $B \subset A$ . Therefore, in order to verify that a STS (B,S(B)) is a subsystem of (A,S(A)) it suffices to show that  $S(B) \subset S(A)$ .

2.1.3 <u>Definition</u>. Let (A,S(A)) and (A,S(A)) be STS. Any one to one mapping f from A onto A such that  $\{a,b,c\}$  is a triple of (A,S(A)) if and only if  $\{f(a),f(b),f(c)\}$  is a triple of (A,S(A)) is called an <u>isomorphism</u> from (A,S(A)) on to (A,S(A)).

2.1.4 <u>Definition</u>. Steiner triple systems (A,S(A)) and (A,S(A)) are said to be <u>isomorphic</u> if there exists an isomorphism from (A,S(A)) onto (A,S(A)).

# 2.2 Elementary Properties of STS

2.2.1 Proposition. Let (A,S(A)), (B,S(B)) and (C,S(C)) be STS. If (C,S(C)), is a subsystem of (B,S(B)) and (B,S(B)) is a subsystem of (A,S(A)), then (C,S(C)) is also a subsystem of (A,S(A)).

<u>Proof</u>: From the hypothesis we have  $S(C) \subset S(B)$  and  $S(B) \subset S(A)$ . Hence  $S(C) \subset S(A)$ . Therefore (C,S(C)) is a subsystem of (A,S(A)).

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2.2.2 <u>Proposition</u>. Let (A,S(A)) be a STS. For any non-empty subset B of A let S(B) denote the family of all triples of (A,S(A)) which are subsets of B. If for any distinct elements x,y in B there exists an element z in B such that  $\{x, y, z\}$  is a triple of (A,S(A)), then (B,S(B)) is a subsystem of (A,S(A)).

<u>Proof</u>: By definition of S(B) we see that S(B) is a family of 3-subsets of B such that  $S(B) \subset S(A)$ . It is left to be shown that (B,S(B)) is a STS. Let x, y be any distinct elements of B. By the hypothesis there exists an element z in B such that  $\{x, y, z\} \in S(A)$ . Hence  $\{x, y, z\}$  is a triple of (A,S(A)) which is a subset of B. Therefore  $\{x, y, z\} \in S(B)$ . Suppose that there exists an element t in B such that  $\{x, y, t\} \in S(B)$ . By definition of S(B) we have  $\{x, y, t\} \in S(A)$ . Since (A,S(A)) is a STS, it follows that t = z. Therefore (B,S(B)) is a STS.

2.2.3 Proposition. Let (B,S(B)) be any subsystem of a STS (A,S(A)). If x and y are elements in A - B and B respectively, then the element z in the triple  $\{x, y, z\}$  of (A,S(A)) belongs to A - B. Proof: Suppose  $z \in B$ . Then y and z are distinct elements of B so that there exists a unique element t in B such that  $\{y,z,t\} \in S(B)$ . Since  $S(B) \subset S(A)$ , it follows that  $\{y,z,t\} \in S(A)$  and thus t = x. Therefore  $x \in B$  which contradicts the assumption that  $x \in A - B$ . Hence  $z \notin B$ . Therefore  $z \in A - B$ .

2.2.4 <u>Definition</u>. Let  $\mathcal{F}$  be a family of STS. By the <u>intersection</u> of the family  $\mathcal{F}$  we mean the ordered pair (I,S), where

$$I = \bigcap \left\{ A / (A, S(A)) \in \mathcal{F} \right\}$$

$$S = \bigcap \left\{ S(A) / (A, S(A)) \in \mathcal{F} \right\}$$

Observe that elements in S are triples that belong to every S(A) of the STS in  $\mathcal{F}$ . Hence triples in S are subsets of every A such that (A,S(A))  $\mathcal{F}$ . Therefore S is a family of 3-subsets of I. From now on we shall write S(I) to stand for S. In general, an intersection of a family of STS need not be a STS.

2.2.5 Proposition. Let C be any non-empty subset of a STS (A,S(A)). Then the intersection (I,S(I)) of all subsystems of (A,S(A)) that contain (I) C is a subsystem of (A,S(A)). Furthermore, (I,S(I)) is the smallest subsystem of (A,S(A)) that contains C.

Proof: Let  $\mathcal{F}$  be the family of all subsystems of (A,S(A)) that contain C. Since each STS in  $\mathcal{F}$  contains C, hence C  $\subset$  I and  $S(I) \subset S(A)$ . We have to show that (I,S(I)), is a STS. Let x,y be distinct elements of I. Since (A,S(A)) is a STS and  $x,y\in A$ , it follows that there exists a unique element z in A such that  $\{x,y,z\}\in S(A)$ . Let (B,S(B)) be any element of  $\mathcal{F}$ . Therefore  $I\subset B$ . Thus x,y are distinct elements of B so that there exists

a unique element z(B) in B such that  $\{x,y,z(B)\} \notin S(B)$ . Since

When we say that a subsystem (B,S(B)) contains C or G is a subset of (B,S(B)) we mean that  $C \subset B$ .

 $S(B) \subset S(A)$ , it follows that  $\{x,y,z(B)\} \in S(A)$  so that z = z(B). Hence  $z \in B$  and  $\{x,y,z\} \in S(B)$ . But B is arbitrary. Hence  $\{x,y,z\} \in S(I)$ . Suppose that t is an element of I such that  $\{x,y,t\} \in S(I)$ . Since  $S(I) \subset S(A)$ , hence  $\{x,y,t\} \in S(A)$  so that t = z. Therefore (I,S(I)) is a subsystem of (A,S(A)).

Let  $(\Lambda_1,S(\Lambda_1))$  be any subsystem of  $(\Lambda,S(\Lambda))$  that contains C. Thus  $(\Lambda_1,S(\Lambda_1))\in\mathcal{F}$ , and hence, I  $\subset$   $\Lambda_1$  and  $S(I)\subset S(\Lambda_1)$ . Therefore (I,S(I)) is the smallest subsystem of  $(\Lambda,S(\Lambda))$  that contains C.

2.2.6 Proposition. Let f be an isomorphism from a STS (A,S(A)) onto a STS (A,S(A)). For any subsystem (R,S(R)) of (A,S(A)), let R be the image of R under f and S(R) be the set of all images of triples of (R,S(R)) under f; i.e.

$$R' = \left\{ f(x) / x \in R \right\}$$

and

$$S(R') = \left\{ \{f(x), f(y), f(z)\} / \{x, y, z\} \in S(R) \right\}$$

Then (R,S(R)) is a subsystem of (A,S(A)).

Proof: By definition  $S(R) \subset S(A)$  and S(R) is a family of 3-subsets of R. To show that (R,S(R)) is a STS, let x,y be any distinct elements of R. Since f(R) = R, it follows that there exists a, b in R such that f(a) = x, f(b) = y. But f is one to one and  $x \neq y$ . Hence a, b are distinct elements of R so that there exists a unique element c in R such that  $\{a,b,c\} \in S(R)$ . From R = f(R), we have  $f(c) \in R$ . By definition of S(R) it follows that  $\{f(a),f(b),f(c)\} \in S(R)$ . Therefore  $\{x,y,f(c)\} \in S(R)$ . Suppose that

u is an element of R such that  $\{x,y,u\} \in S(R)$ . Since f(R) = R, hence there exists an element d in R such that f(d) = u. Consequently  $\{a,b,d\} \in S(R)$ . As a result we have d = c so that u = f(c). Hence (R,S(R)) is a STS. Therefore (R,S(R)) is a subsystem of (A,S(A)).

As a consequence of the above proposition, we have

2.2.7 <u>Corollary</u>. If (A,S(A)) and (A,S(A)) are isomorphic STS such that (A,S(A)) contains a subsystem of order n, then (A,S(A)) also contains a subsystem of order n.

2.2.8 <u>Proposition</u>. Let  $(\Lambda, S(\Lambda))$  be a STS of order n. Then every element of  $\Lambda$  is contained in  $\frac{n-1}{2}$  triples of  $(\Lambda, S(\Lambda))$ .

Proof: Let x be any element of A and let

$$T_x = \{ T \in S(A) / x \in T \}$$

Hence x is contained in  $|T_x|$  triples of (A,S(A)). For any  $T = \left\{ x,y,z \right\} \in T_x$  we can form two 2-subsets of A that contain x; namely  $\left\{ x,y \right\}$  and  $\left\{ x,z \right\}$ . Furthermore, any two triples in  $T_x$  have x as only their common elements. Therefore different triples give rise to entirely different 2-subsets of A that contain x. Hence the total number of 2-subsets of A that contain x formed from the triples in  $T_x$  is exactly  $2 \mid T_x \mid$ . On the other hand, the total number of 2-subsets of A that contain x is n - 1. But for any 2-subset B of A that contains x there must exists a unique  $T \in T_x$  such that B  $\subseteq T$ . Hence  $2 \mid T_x \mid = n-1$  so that  $\mid T_x \mid = \frac{n-1}{2}$ . Since x is arbitrary, it follows that every element of A is

contained in nol triples:

2.2.9 Proposition. The total number of triples in any STS of order n is  $\frac{1}{6}$  n(n - 1).

Proof: Let  $(\Lambda_i S(A))$  be any STS of order  $n_i$ . Assume that S(A) contains exactly k triples. Let  $S(A) = \left\{\begin{array}{c} A_1, A_2, \ldots, A_k \\ \end{array}\right\}$ . For any  $A_i$ , the total number of 2-subsets of  $A_i$  is 3. Since any 2-subset of A is a subset of one and only one  $A_i$ , it follows that the total number of 2-subsets of  $\bigcup_{i=1}^k A_i = A$  is 3k. On the other hand the total number of 2-subset of A is  $\frac{1}{2}$  n(n-1). Hence  $3k = \frac{1}{2}$  n(n-1) so that  $k = \frac{1}{6}$  n(n-1).

## 2.3 Necessary Condition for the Existence of STS

When a positive integer n is given, we would like to know whether we can construct a STS of order n. It turns out that STS of order n do not exist for infinitely many values of n. A necessary condition for the existence of STS of order n is given in the following theorem.

2.3.1 Theorem. If a STS of order n exists, then  $(2.3.1) \quad n \equiv 1 \text{ or } 3 \pmod{6}$ 

Proof: Since  $\frac{n(n-1)}{6}$  is a positive integer, hence n(n-1) is divisible by 3. Therefore n or n-1 must be divisible by 3.

First, let us suppose that n is divisible by 3. In this case we have n = 3m for some positive integer m. Since  $\frac{n-1}{2}$  is a positive integer, it follows that n - 1 = 2t for some positive

integer t. Therefore 3m - 1 = 2t. From this it follows that m must be odd. Let m = 2s + 1, where s is a positive integer. Hence n = 3m = 3(2s + 1) = 6s + 3. Therefore we have  $n \equiv 3 \pmod{6}$ .

Next, we suppose that n-1 is divisible by 3. Then n-1=3m for some positive integer m. Since  $\frac{n-1}{2}$  is a positive integer, hence n-1=2t for some positive integer t. Therefore 3m=2t. From this it follows that m must be even. Let m=2s where s is a positive integer. Hence n=3m+1=3(2s)+1=6s+1. Thus we have  $n\equiv 1\pmod 6$ .

Therefore  $n \equiv 1$  or 3 (mod 6)

In fact this necessary condition is also sufficient. This will be proved in Chapter IV.