

CHAPTER II

PRELIMINARIES

In this chapter we shall collect some definitions and results from topology and group theory which will be a basic requirement for our investigation. The materials of this chapter were extracted from references [2], [3], [4], [5]. We shall assume that the reader is familiar with common terms used in the set theory.

2.1 Algebraic Concepts

By a group we mean an ordered pair (G, o) , where G is a non - empty set and o is a binary operation on G satisfying the following conditions :

- (i) For all x, y, z of G , $xo(yoz) = (xoy)oz$
- (ii) There exists an element e of G such that
 $eo x = xoe = x$ for each x in G .
- (iii) For each x in G , there is an element x^{-1} in G such that $xox^{-1} = e = x^{-1}ox$.

For convenience, we shall denote the group (G, o) simply by G . It can be shown that the element e in (ii) is unique, it is known as the identity of G . For each x in G , the element x^{-1} in (iii) is also unique. It is known as the inverse of x .

A group G is abelian or commutative, if and only if $xoy = yox$ for all elements x, y of G . The number of elements in a group G shall be called the order of G and denoted by $|G|$. G is called finite or infinite as its order is finite or infinite. For any element x in G , the order of x is the least positive integer m such that $x^m = e$. If no such integer exists we say that x is of infinite order. If G is a group in which every element is of order 2, G is said to be a boolean group, otherwise, it is said to be a non-boolean group. A boolean group G of order 4 is also known as the Klein four group. It can be shown that any boolean group G is also abelian. If for each x in G there exists y in G such that $x = yoy$, G is said to be a 2-divisible group. A group H is a subgroup of G if and only if $H \subset G$ and the group operation of H is the restriction of that of G . It can be shown that any non-empty set H forms a subgroups of (G, o) if and only if $xoy^{-1} \in H$ for any x, y in H . If H is a subgroup of a group G and x, y are elements of G such that $xy^{-1} \in H$, we say that x is right congruent to y modulo H and denoted by $x \widetilde{H}R y$. If $x^{-1}y \in H$, we say that x is left congruent to y modulo H and denoted by $x \widetilde{H}L y$. If $\widetilde{H}R$ and $\widetilde{H}L$ are coincide we shall denote them by \widetilde{H} . It can be shown that left (right) congruence modulo H is an equivalence relation on G . The equivalence class of $x \in G$ under left(right) congruence modulo H is the set $xH = \{xh : h \in H\}$ ($Hx = \{hx : h \in H\}$), it is called a left(right) coset of H in G . It follows that $G = \cup xH = \cup Hx$ where the union is taken over all pairwise

disjoint cosets. The number of distinct left(right) cosets of H in G is called the index of H in G and denoted by $[G:H]$. If H is a subgroup of G such that left and right congruence modulo H coincide, then H is said to be a normal subgroup of G . In an abelian group, each subgroup is normal. If H is a normal subgroup of a group G , then G/H is a group of order $[G:H]$ under the binary operation given by $(xH)(yH) = xyH$, this group is called the quotient group of G by H , and will be denoted by G/H .

A mapping h on a group (G, \circ) into a group $(G, *)$ is said to be a homomorphism provided

$$h(x \circ y) = h(x) * h(y), \text{ for all } x, y \text{ in } G.$$

If h is bijective, h is called an isomorphism.

By a field we mean a triple $(F, +, \cdot)$, where $+$, \cdot are two binary operations on F , known as addition and multiplication respectively, such that the followings hold :

- (i) F forms a commutative group under addition.
- (ii) $F^* = F - \{0\}$, where 0 is the additive identity forms a commutative group under multiplication.
- (iii) For any $a, b, c \in F$, we have

$$a(b+c) = ab + ac .$$

For convenience, we shall denote a field $(F, +, \cdot)$ simply by F . $(F, +)$ and (F^*, \cdot) will be referred to as the additive group and the multiplicative group of F , respectively. If there is a least positive integer n such that $na = 0$ for all $a \in F$, then F is said to have characteristic n . If no such n exists F is said to have characteristic zero. If K is any non - empty subset of a field $(F, +, \cdot)$ such that K form a field under restriction of $+, \cdot$ to $K \times K$, we say that $(K, +, \cdot)$ is a subfield of $(F, +, \cdot)$. If K is a subfield of F , we say that F is an extension field of K .

A function φ of a field F into a field K is a homomorphism provided that for all $a, b \in F$:

$$\varphi(a+b) = \varphi(a) + \varphi(b) \quad \text{and} \quad \varphi(ab) = \varphi(a)\varphi(b) .$$

If φ is bijective, φ is called an isomorphism. If φ is an isomorphism of F into itself, φ is called an automorphism. If F is a field in which $a^2 \neq -1$ for any $a \in F$, let

$$C(F) = \left\{ (a, b) : a \text{ and } b \text{ are elements of } F \right\} .$$

Define addition and multiplication on $C(F)$ as follows :

$$(a, b) + (c, d) = (a + c, b + d) ,$$

and

$$(a, b)(c, d) = (ac - bd, ad + bc) .$$

It can be shown that $C(F)$ under the above addition and multiplication forms a field. This field contains $\bar{F} = \{(a,0) : a \in F\}$ as a subfield isomorphic to F . Hence we may view F as a subfield of $C(F)$. Observe that if we denote the element $(a,0)$ of F by a and denote $(0,1)$ by i , then each element (a,b) of $C(F)$ can be expressed as

$$\begin{aligned}(a, b) &= (a,0) + (b, 0)(0,1) \\ &= a + bi .\end{aligned}$$

Note that from the definition of i , we have $i^2 = (-1, 0) = -1$. It can be shown that the mapping $\psi : C(F) \rightarrow C(F)$ given by

$$\psi(a+bi) = a - bi ,$$

is the unique automorphism of $C(F)$ fixing all elements of \bar{F} and taking i into $-i$. Since \bar{F} is isomorphic to F , hence we may view ψ as the automorphism of $C(F)$ fixing all elements of F and taking i into $-i$. Let

$$\Delta(F) = \{a + bi \in C(F) : (a + bi)\psi(a + bi) = 1\}.$$

It can be shown that $\Delta(F)$ forms a multiplicative subgroup of $C(F)^*$. To each field F , we shall associate a multiplicative group $M(F)$ as follows : if F contains an element i such that $i^2 = -1$, we let $M(F) = F^*$; if F contains no element i such that $i^2 = -1$, we let $M(F) = \Delta(F)$.

Lemma 2.1.1 Let G be a group, F be a field of characteristic different from 2 such that $a^2 \neq -1$ for any a in F . Let h be a homomorphism from G into $C(F)^*$. Then for each x in G , $\frac{h(x) + h(x^{-1})}{2}$ and $\frac{h(x) - h(x^{-1})}{2i}$ belong to F if and only if

$h(x)$ belongs to $\Delta(F)$.

Proof Let φ be the automorphism of $C(F)$ fixing all elements of F and taking i into $-i$.

Assume that $h : G \rightarrow C(F)^*$ is a homomorphism such that $\frac{h(x) + h(x^{-1})}{2}$ and $\frac{h(x) - h(x^{-1})}{2i}$ belong to F .

Therefore

$$\begin{aligned} \frac{h(x) + h(x^{-1})}{2} &= \varphi\left(\frac{h(x) + h(x^{-1})}{2}\right), \\ &= \frac{\varphi(h(x)) + \varphi(h(x^{-1}))}{2}, \end{aligned}$$

thus,

$$(2.1.1.1) \quad h(x) + h(x^{-1}) = \varphi(h(x)) + \varphi(h(x^{-1})).$$

Also,

$$\begin{aligned} \frac{h(x) - h(x^{-1})}{2i} &= \varphi\left(\frac{h(x) - h(x^{-1})}{2i}\right), \\ &= \frac{\varphi(h(x)) - \varphi(h(x^{-1}))}{-2i}, \end{aligned}$$

thus

$$(2.1.1.2) \quad h(x) - h(x^{-1}) = \psi(h(x^{-1})) - \psi(h(x)).$$

It follows from (2.1.1.1) and (2.1.1.2) that

$$2h(x) = 2\psi(h(x^{-1})).$$

Hence
$$h(x) \cdot \psi(h(x)) = 1.$$

Therefore $h(x)$ belongs to $\Delta(F)$.

Conversely, assume that h is a homomorphism from G into $\Delta(F)$.

Hence $h(x) \cdot \psi(h(x)) = 1$ for all x in G . It follows that

$$\psi(h(x)) = h(x)^{-1} = h(x^{-1}).$$

Let $h(x) = a + bi$ where $a, b \in F$. Therefore,

$$\begin{aligned} \frac{h(x) + h(x^{-1})}{2} &= \frac{h(x) + \psi(h(x))}{2} \\ &= \frac{(a + bi) + (a - bi)}{2} \\ &= a, \end{aligned}$$

and

$$\begin{aligned} \frac{h(x) - h(x^{-1})}{2i} &= \frac{h(x) - \psi(h(x))}{2i} \\ &= \frac{(a + bi) - (a - bi)}{2i} \\ &= b. \end{aligned}$$

Hence $\frac{h(x) + h(x^{-1})}{2}$ and $\frac{h(x) - h(x^{-1})}{2i}$ belong to F .

Let $(F, +, \cdot)$ be a field and $(V, +)$ be a commutative group with a rule of multiplication which assigns to any $a \in F, u \in V$, a product $au \in V$. Then V is called a vector space over F if the following axioms hold :

- 1) For any $a \in F$ and any $u, v \in V$, $a(u+v) = au + av$.
- 2) For any $a, b \in F$ and any $u \in V$, $(a+b)u = au + bu$.
- 3) For any $a, b \in F$ and any $u \in V$, $a(bu) = (ab)u$.
- 4) For $v \in V$, $1v = v$ where 1 is the multiplicative identity of F .

The elements of F and V will be referred to as scalars and vectors, respectively. If V is a vector space over the field F and $\{x_i\}$ ($1 \leq i \leq n$) is a finite subset of V , then for $a_i \in F, 1 \leq i \leq n$, $\sum_{i=1}^n a_i x_i$ is called a linear

combination of the x_i . The vectors $x_1, \dots, x_n \in V$ are said to be linearly dependent over F , or simply dependent, if there exist scalars $a_1, \dots, a_n \in F$, not all of them zero, such that $\sum_{i=1}^n a_i x_i = 0$. An arbitrary set A of

vectors is said to be a linearly dependent set if some finite subset of A is linearly dependent. Otherwise, the set A is called linearly independent or simply independent. If \mathcal{B}

is a linearly independent subset of V such that for every $v \in V$, v can be written as a linear combination of vectors in \mathcal{B} , we say that \mathcal{B} is a basis of V . It can be shown that every vector in V has a unique representation as a linear combination of elements of any basis \mathcal{B} .

Observe that the set \mathbb{R} of real numbers can be considered as a vector space over the field \mathbb{Q} of rational numbers. It can be shown that \mathbb{R} has a basis over \mathbb{Q} . Such a basis is known as a Hamel basis. A proof of the existence of such a basis is given in [6].

2.2 Topological Concepts

Let X be a set and \mathcal{T} be a collection of subsets of X . The collection \mathcal{T} is called a topology on X provided \mathcal{T} satisfies the following conditions :

- a) X and \emptyset are elements of \mathcal{T} .
- b) The intersection of any two members of \mathcal{T} is in \mathcal{T} .
- c) The arbitrary union of members of \mathcal{T} is in \mathcal{T} .

If \mathcal{T} is a topology on a set X , then (X, \mathcal{T}) is said to be a topological space. Occasionally, we shall denote any topological space (X, \mathcal{T}) simply by X . The members of \mathcal{T} are called \mathcal{T} -open sets of X , or simply open sets of X . If a topological space X has the property that for any x, y in X there exist open sets O_1, O_2 such that $x \in O_1, y \in O_2$ and

$x \notin O_2, y \notin O_1$, we say that X is a T_1 - space. For any topological space (X, \mathcal{J}) , it can be shown that if Y is any subset of X , then the family $\mathcal{J}_Y = \{T \cap Y : T \in \mathcal{J}\}$ is a topology on Y ; it is called the relative topology of Y and the topological space (Y, \mathcal{J}_Y) is called a subspace of (X, \mathcal{J})

A subcollection \mathcal{B} of a topology \mathcal{J} is said to be a base of \mathcal{J} provided the following condition hold : for each $T \in \mathcal{J}$ and $x \in T$, there exists $B \in \mathcal{B}$ such that $x \in B \subset T$, or equivalently, each T in \mathcal{J} is a union of members of \mathcal{B} . It can be shown that if a family \mathcal{B} of subsets of a set X has the properties ;

(i) the union of sets in \mathcal{B} is in X ,

(ii) for each $B_1, B_2 \in \mathcal{B}$, $B_1 \cap B_2$ is the union of members of \mathcal{B} , then \mathcal{B} is a base for some topology for X .

This topology consists of all sets that can be written as unions of sets in \mathcal{B} . Observe that the family of all open intervals form a base for a topology on the set \mathbb{R} of real numbers. This topology is known as the usual topology on \mathbb{R} .

A subfamily \mathcal{S} of \mathcal{J} is a subbase of the topology \mathcal{J} on X if and only if the set of all finite intersections of members of \mathcal{S} form a base for \mathcal{J} .

Let $\{X_\alpha : \alpha \in A\}$ be a family of sets. $X = \prod_{\alpha \in A} X_\alpha$

denotes the set of all mappings $x: A \rightarrow \bigcup_{\alpha \in A} X_\alpha$ such that

$x(\alpha) \in X_\alpha$ for each $\alpha \in A$. X is called the Cartesian product or product of X_α 's. For each $x \in X$ and each $\alpha \in A$, $x(\alpha)$ is called the α -th coordinate of x . We shall denote $x(\alpha)$ by x_α . The mapping $P_\alpha : X \rightarrow X_\alpha$ defined by $P_\alpha(x) = x_\alpha$, is called the α -th projection. It can be seen that P_α is a mapping from X onto X_α . If $\{X_\alpha : \alpha \in A\}$ is a family of topological spaces, then the family of sets of the form $P_\alpha^{-1}(T_\alpha)$, where T_α is a \mathcal{J}_α -open set, forms a subbase of a topology \mathcal{J} for the product $\prod_{\alpha \in A} X_\alpha$. This topology is known as the product topology. The topological space

$(\prod_{\alpha \in A} X_\alpha, \mathcal{J})$ will be called the product space of $\{X_\alpha : \alpha \in A\}$.

Let X and Y be two topological spaces. A mapping f of X into Y is said to be continuous if for each open set V in Y , $f^{-1}[V] = \{x \in X : f(x) \in V\}$ is an open set of X . If for each open set U in X , $f(U) = \{f(x) : x \in U\}$ is an open set of Y , f is said to be open.

Let X be a topological space, R be an equivalence relation on X and $Y = X/R$ be the quotient set of X with respect to the relation R . The mapping $\varphi : X \rightarrow Y$ defined by $\varphi(x) = \bar{x}$, where \bar{x} denotes the equivalence class of x , will be called the canonical mapping. It can be shown that the family

$\mathcal{J}_\varphi = \{V \subset Y : \varphi^{-1}(V) \text{ is open}\}$ is a topology on Y ;



it is called the quotient topology and $(Y, \mathfrak{J}_\varphi)$ is called the quotient space of X by R .

2.3 Topological Groups

A triple (G, o, \mathfrak{J}) is a topological group if and only if (G, o) is a group, (G, \mathfrak{J}) is a topological space and the function whose value at a member (x, y) of $G \times G$ is xoy^{-1} is continuous relative to the product topology for $G \times G$. We sometimes say " G is a topological group".

The followings are examples of topological groups :

(a) The set \mathbb{R} of real numbers with addition as the group operation and the usual topology form a topological group.

(b) The set \mathbb{Z} of integers with addition as the group operation and the relative topology of the usual topology of \mathbb{R} form a topological group.

(c) The set \mathbb{R}^* of nonzero real numbers with multiplication as the group operation and the relative topology of the usual topology of \mathbb{R} form a topological group.

(d) The set \mathbb{R}^+ of positive real numbers with multiplication as the group operation and the relative topology of the usual topology of \mathbb{R} form a topological group.

(e) The set \mathbb{R}^n of all real n -tuples with an addition as the coordinate addition and the usual topology of \mathbb{R} form a topological group.

(f) A **complex** number can be considered as an ordered pair of real numbers. Hence the usual topology on \mathbb{C} , the set of complex numbers, shall mean the usual topology on \mathbb{R}^2 . The set \mathbb{C} of complex numbers with addition as a group operation and the usual topology on \mathbb{C} form a topological group

(g) The set \mathbb{C}^* of nonzero complex numbers with complex multiplication as a group operation and the relative topology of the usual topology of \mathbb{C} form a topological group.

(h) The unit circle $\Delta = \{ z \in \mathbb{C} : |z| = 1 \}$ with complex multiplication as the group operation and the relative topology of the usual topology of \mathbb{C} form a topological group.

If H is a subgroup of G , H endowed with the relative topology is a topological group; it is called a topological subgroup or simply a subgroup of G . If H is a normal subgroups of G , then G/H , the quotient group with respect to the equivalence relation \tilde{H} , and the quotient topology form a topological group; it is called the quotient group of G by \tilde{H} . It can be shown that H is open if and only if each coset of H is open.

If φ is the canonical mapping of G onto G/H , it can be shown that φ is an open continuous homomorphism of G onto G/H . The following is a fact about continuous homomorphism.

We state this fact for later reference, and it can be seen in [1].

Theorem 2.3.1 Every continuous homomorphism of \mathbb{R} into \mathbb{R}/\mathbb{Z} is of the form $x \mapsto \varphi(ax)$ where $a \in \mathbb{R}$ and $\varphi : \mathbb{R} \rightarrow \mathbb{R}/\mathbb{Z}$ is the canonical mapping .

2.4 Topological Fields.

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A topological field is a quadruple $(F, +, \cdot, \mathcal{J})$ such that $(F, +, \cdot)$ is a field, $(F, +, \mathcal{J})$ and $(F^*, \cdot, \mathcal{J}_{F^*})$ are topological groups where \mathcal{J}_{F^*} is the topology induced by \mathcal{J} on F^* .

We sometimes say " F is a topological field ". If F is a topological field in which $a^2 + 1 \neq 0$ for all $a \in F$, then $C(F)$ endowed with the product topology is a topological field. It can be shown that the multiplicative subgroup $\Delta(F)$ with the relative topology form a topological group.

2.5 Topological Vector Spaces.

A topological vector space is the vector space V over the field F of real or complex numbers and a topology \mathcal{J} on V such that the function $f : V \times V \rightarrow V$ and $g : F \times V \rightarrow V$ defined by $f(x, y) = x+y$ and $g(\lambda, x) = \lambda x$, are continuous, where the topology on F is the usual topology. The topology \mathcal{J} is said to be a vector topology.