

References

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Appendix

Geometric figures and numerical minimization values in this research can be obtained from the following code by using Mathematica5.0

For equilateral triangle case

```

d[xys_] :=
  If[Length[xys] == 2,  $\sqrt{(xys[[1, 1]] - xys[[2, 1]])^2 + (xys[[1, 2]] - xys[[2, 2]])^2}$ ,
  d[xys[[{1, 2}]]] + d[Rest[xys]]]

u[ $\theta$ ] := {Cos[ $\theta$ ], Sin[ $\theta$ ]}; dd[xy_,  $\theta$ ] := xy.u[ $\theta$ ]; sqrt3 =  $\sqrt{3}$ ;

p1 = {x1, y1}; p1b = {x1b, y1b}; p2 = {x2, y2};
p3 = {x3, y3}; p4 = {x4, y4}; p5 = {x5, y5}; p6 = {x6, y6};

m = sqrt3; y1 = 0; y1b = 0; y2 = m x2; y3 = -m (x3 - 1); y4 = yA2; y5 = m (x5 - xA2) + yA2;
N[ $\sqrt{28/27}$ ]
N[ $\sqrt{27/28}$ ]

 $\alpha = 60^\circ$ ;  $\beta = 60^\circ$ 

AB =  $\frac{0.5}{\text{Sin}[\alpha]}$ ;
A1 = {0, 0}; C1 = {1, 0}; B1 = AB u[ $\alpha$ ];
A2 = {xA2, yA2}; C2 = {xA2 - 1, yA2}; B2 = A2 + AB u[ $180^\circ + \alpha$ ];

u[ $\theta$ ] = {Cos[ $\theta$ ], Sin[ $\theta$ ]};
Cross3[{x1_, y1_}, {x2_, y2_}] = x1 y2 - x2 y1;
OnRight[R_, P_, Q_] = Cross3[R - P, Q - P] > 0;
cond3 = OnRight[p3, C1, B1];
cond6 = dd[p6 - A2,  $210^\circ$ ] >  $\sqrt{3}/2$ 
condt1 = y4 < dd[p5 - p2,  $\alpha - 90^\circ$ ];

draw[arc_, eval_] :=
  Show[Graphics[{{RGBColor[0, 1, 0], Line[{{(0, 0), {1, 0}}, u[ $60^\circ$ ], {0, 0}}]},
  {RGBColor[0, 0, 1], Line[{{xA2, yA2}, {xA2 - 1, yA2}, {xA2, yA2} - u[ $60^\circ$ ],
  {xA2, yA2}}]}, {Thickness[.004], Line[arc]}] /. eval],
  AspectRatio -> Automatic, PlotRange -> {{-1, 2}, {-1, 2}}]

```

```

nm6 = {1, {x1 → 0.9999999955000765, x2 → 0.49999999589579347,
  x3 → 0.5000000005195876, x4 → 0.49999999529808775,
  x5 → 0.9999999948223148, x6 → 0.9999999906035069, xA2 → 1.4999999919558042,
  y6 → -3.422141170023855*^-9, yA2 → 0.8660253988581608}};
model6origin[nm0_, seq_, cond_, iter_, meth_] := {
  nm = NMinimize[{d[seq], cond3, cond6} ∪ cond,
    {{x1, x1 /. nm0[[2]], (x1 /. nm0[[2]]) + .000001},
    {x2, x2 /. nm0[[2]], (x2 /. nm0[[2]]) + .000001},
    {x3, x3 /. nm0[[2]], (x3 /. nm0[[2]]) + .000001}, {x4, x4 /. nm0[[2]],
    (x4 /. nm0[[2]]) + .000001}, {x5, x5 /. nm0[[2]], (x5 /. nm0[[2]]) + .000001},
    {x6, x6 /. nm0[[2]], (x6 /. nm0[[2]]) + .000001}, {y6, y6 /. nm0[[2]],
    (y6 /. nm0[[2]]) + .000001}, {xA2, xA2 /. nm0[[2]], (xA2 /. nm0[[2]]) + .000001},
    {yA2, yA2 /. nm0[[2]], (yA2 /. nm0[[2]]) + .000001}},
  MaxIterations → iter, Method → meth],
  draw[seq, nm[[2]]];}
model6[seq_, cond_, iter_] := model6origin[nm6, seq, cond, iter, Automatic]
model6again[seq_, cond_, iter_] := model6origin[nm, seq, cond, iter, Automatic]
model6DE[seq_, cond_, iter_] :=
  model6origin[nm6, seq, cond, iter, DifferentialEvolution]
model6againDE[seq_, cond_, iter_] :=
  model6origin[nm, seq, cond, iter, DifferentialEvolution]
model6NM[seq_, cond_, iter_] := model6origin[nm6, seq, cond, iter, NelderMead]
model6againNM[seq_, iter_] := model6origin[nm, seq, iter, NelderMead]

nm6e = {1, {x1 → 0.9999999955000765, x2 → 0.49999999589579347,
  x3 → 0.5000000005195876, x4 → 0.49999999529808775,
  x5 → 0.9999999948223148, x6 → 0.9999999906035069, xA2 → 1.4999999919558042,
  y6 → -3.422141170023855*^-9, yA2 → 0.8660253988581608}};
model6eorigin[nm0_, seq_, cond_, iter_, meth_] := {x4 = x1;
  nm = NMinimize[{d[seq], cond3, cond6} ∪ cond,
    {{x1, x1 /. nm0[[2]], .000001 + x1 /. nm0[[2]]},
    {x2, x2 /. nm0[[2]], (x2 /. nm0[[2]]) + .000001},
    {x3, x3 /. nm0[[2]], (x3 /. nm0[[2]]) + .000001},
    {x5, x5 /. nm0[[2]], (x5 /. nm0[[2]]) + .000001}, {x6, x6 /. nm0[[2]],
    (x6 /. nm0[[2]]) + .000001}, {y6, y6 /. nm0[[2]], (y6 /. nm0[[2]]) + .000001},
    {xA2, xA2 /. nm0[[2]], (xA2 /. nm0[[2]]) + .000001}, {yA2, yA2 /. nm0[[2]],
    (yA2 /. nm0[[2]]) + .000001}}, MaxIterations → iter, Method → meth],
  draw[seq, nm[[2]]];, x4 =.}
model6e[seq_, cond_, iter_] := model6eorigin[nm6e, seq, cond, iter, Automatic]
model6eagain[seq_, cond_, iter_] := model6eorigin[nm, seq, cond, iter, Automatic]
model6eDE[seq_, cond_, iter_] :=
  model6eorigin[nm6e, seq, cond, iter, DifferentialEvolution]
model6eagainDE[seq_, cond_, iter_] :=
  model6eorigin[nm, seq, cond, iter, DifferentialEvolution]
model6eNM[seq_, cond_, iter_] := model6eorigin[nm6e, seq, cond, iter, NelderMead]
model6eagainNM[seq_, iter_] := model6eorigin[nm, seq, iter, NelderMead]

```

```

nm7 = {1, {x1 → 9.407630605393444*^-16, x1b → 0.9999997952025184,
  x2 → 2.839455236460388*^-15, x3 → 0.9999999366622955, x4 → 0.9999999366622953,
  x5 → 0.99999979520251, x6 → -2.8718226404576984*^-16, xA2 → 0.9999998585402131,
  y6 → 8.093426830227416*^-16, yA2 → 1.097041192074698*^-7}};
model7origin[nm0_, seq_, cond_, iter_, meth_] :=
{nm = NMinimize[{d[seq], cond3, cond6, x1 < x4 < x1b} ∪ cond,
  {{x1, x1 /. nm0[[2]], (x1 /. nm0[[2]]) + .000001}, {x1b, x1b /. nm0[[2]],
  (x1b /. nm0[[2]]) + .000001}, {x2, x2 /. nm0[[2]], (x2 /. nm0[[2]]) + .000001},
  {x3, x3 /. nm0[[2]], (x3 /. nm0[[2]]) + .000001}, {x4, x4 /. nm0[[2]],
  (x4 /. nm0[[2]]) + .000001}, {x5, x5 /. nm0[[2]], (x5 /. nm0[[2]]) + .000001},
  {x6, x6 /. nm0[[2]], (x6 /. nm0[[2]]) + .000001}, {y6, y6 /. nm0[[2]],
  (y6 /. nm0[[2]]) + .000001}, {xA2, xA2 /. nm0[[2]], (xA2 /. nm0[[2]]) + .000001},
  {yA2, yA2 /. nm0[[2]], (yA2 /. nm0[[2]]) + .000001}},
  MaxIterations → iter, Method → meth],
  draw[seq, nm[[2]]];}
model7[seq_, cond_, _iter_] := model7origin[nm7, seq, cond, iter, Automatic]
model7again[seq_, cond_, iter_] := model7origin[nm, seq, cond, iter, Automatic]
model7DE[seq_, cond_, iter_] :=
  model7origin[nm7, seq, cond, iter, DifferentialEvolution]
model7againDE[seq_, cond_, iter_] :=
  model7origin[nm, seq, cond, iter, DifferentialEvolution]
model7NM[seq_, cond_, iter_] := model7origin[nm7, seq, cond, iter, NelderMead]
model7againNM[seq_, iter_] := model7origin[nm, seq, iter, NelderMead]

```

For an isosceles righted angled triangle,

```

d[xys_] :=
  If[Length[xys] == 2,  $\sqrt{(xys[[1, 1]] - xys[[2, 1]])^2 + (xys[[1, 2]] - xys[[2, 2]])^2}$ ,
    d[xys[{{1, 2}}]] + d[Rest[xys]]]

u[ $\theta$ _] := {Cos[ $\theta$ ], Sin[ $\theta$ ]}; dd[xy_,  $\theta$ _] := xy.u[ $\theta$ ]; sqrt3 =  $\sqrt{3}$ ;

p1 = {x1, y1}; p1b = {x1b, y1b}; p2 = {x2, y2};
p3 = {x3, y3}; p4 = {x4, y4}; p5 = {x5, y5}; p6 = {x6, y6};

m = 1; y1 = 0; y1b = 0; y2 = m x2; y3 = -m (x3 - 1); y4 = yA2; y5 = m (x5 - xA2) + yA2;
N[ $\frac{\sqrt{2}}{2}$ ]
0.707107

 $\alpha = 45^\circ$ ;  $\beta = 45^\circ$ 

45 °

AB =  $\frac{0.5}{\text{Sin}[\alpha]}$ ;
A1 = {0, 0}; C1 = {1, 0}; B1 = AB u[ $\alpha$ ];
A2 = {xA2, yA2}; C2 = {xA2 - 1, yA2}; B2 = A2 + AB u[180 ° +  $\alpha$ ];

u[ $\theta$ _] = {Cos[ $\theta$ ], Sin[ $\theta$ ]};
Cross3[{x1_, y1_}, {x2_, y2_}] = x1 y2 - x2 y1;
OnRight[R_, P_, Q_] = Cross3[R - P, Q - P] > 0;
cond3 = OnRight[p3, C1, B1];
cond6 = dd[p6 - A2, 225 °] >  $\sqrt{2}/2$ 
condt1 = y4 < dd[p5 - p2,  $\alpha - 90^\circ$ ];

 $-\frac{x6 - xA2}{\sqrt{2}} - \frac{y6 - yA2}{\sqrt{2}} > \frac{1}{\sqrt{2}}$ 

```

```

draw[arc_, eval_] :=
  Show[Graphics[{{RGBColor[0, 1, 0], Line[{{(0, 0), (1, 0),  $\frac{\sqrt{2}}{2}$  u[45°], (0, 0)}]},
    {RGBColor[0, 0, 1], Line[{{xA2, yA2}, {xA2 - 1, yA2}, {xA2, yA2} -  $\frac{\sqrt{2}}{2}$  u[45°],
      {xA2, yA2}]}}], {Thickness[.004], Line[arc]}] /. eval],
  AspectRatio → Automatic, PlotRange → {{-.5, 1.5}, {-.5, .6}}]

x1 → .5, x2 → .3, x3 → .7, x4 → .5, x5 → .7, x6 → .2, y6 → .1, xA2 → 1, yA2 → .4

nm6 = {1, {x1 → 0.9999518184201992, x2 → 0.5000302980145336, x3 → 0.9999809691454545,
  x4 → 0.5001300062320384, x5 → 0.9999721408382596, x6 → 0.5000580797878551,
  xA2 → 1.5000124273771929, y6 → 0.5000051033922595, yA2 → 0.5000541115504397}};
model6origin[nm0_, seq_, cond_, iter_, meth_] := {
  nm = NMinimize[{d[seq], cond3, cond6} ∪ cond,
    {{x1, x1 /. nm0[[2]], (x1 /. nm0[[2]]) + .000001},
    {x2, x2 /. nm0[[2]], (x2 /. nm0[[2]]) + .000001},
    {x3, x3 /. nm0[[2]], (x3 /. nm0[[2]]) + .000001}, {x4, x4 /. nm0[[2]],
    (x4 /. nm0[[2]]) + .000001}, {x5, x5 /. nm0[[2]], (x5 /. nm0[[2]]) + .000001},
    {x6, x6 /. nm0[[2]], (x6 /. nm0[[2]]) + .000001}, {y6, y6 /. nm0[[2]],
    (y6 /. nm0[[2]]) + .000001}, {xA2, xA2 /. nm0[[2]], (xA2 /. nm0[[2]]) + .000001},
    {yA2, yA2 /. nm0[[2]], (yA2 /. nm0[[2]]) + .000001}},
  MaxIterations → iter, Method → meth],
  draw[seq, nm[[2]]];}
model6[seq_, cond_, iter_] := model6origin[nm6, seq, cond, iter, Automatic]
model6again[seq_, cond_, iter_] := model6origin[nm, seq, cond, iter, Automatic]
model6DE[seq_, cond_, iter_] :=
  model6origin[nm6, seq, cond, iter, DifferentialEvolution]
model6againDE[seq_, cond_, iter_] :=
  model6origin[nm, seq, cond, iter, DifferentialEvolution]
model6NM[seq_, cond_, iter_] := model6origin[nm6, seq, cond, iter, NelderMead]
model6againNM[seq_, iter_] := model6origin[nm, seq, iter, NelderMead]

```

```

nm6e =
  {1, {x1 → 0.5482300155267756, x2 → 0.0021675964880911993, x3 → 0.999998147335638,
    x5 → 0.9999981473356386, x6 → 0.0021675964880911803, xA2 → 1.0021657419609227,
    y6 → 0.002167596488091243, yA2 → 0.002169447289645611}};
model6origin[nm0_, seq_, cond_, iter_, meth_] := {x4 = x1;
  nm = NMinimize[{d[seq], cond3, cond6} ∪ cond,
    {{x1, x1 /. nm0[[2]], (x1 /. nm0[[2]]) + .000001},
     {x2, x2 /. nm0[[2]], (x2 /. nm0[[2]]) + .000001},
     {x3, x3 /. nm0[[2]], (x3 /. nm0[[2]]) + .000001},
     {x5, x5 /. nm0[[2]], (x5 /. nm0[[2]]) + .000001}, {x6, x6 /. nm0[[2]],
     (x6 /. nm0[[2]]) + .000001}, {y6, y6 /. nm0[[2]], (y6 /. nm0[[2]]) + .000001},
     {xA2, xA2 /. nm0[[2]], (xA2 /. nm0[[2]]) + .000001}, {yA2, yA2 /. nm0[[2]],
     (yA2 /. nm0[[2]]) + .000001}}, MaxIterations → iter, Method → meth],
  draw[seq, nm[[2]]];, x4 = .]
model6e[seq_, cond_, iter_] := model6origin[nm6e, seq, cond, iter, Automatic]
model6eagain[seq_, cond_, iter_] := model6origin[nm, seq, cond, iter, Automatic]
model6eDE[seq_, cond_, iter_] :=
  model6origin[nm6e, seq, cond, iter, DifferentialEvolution]
model6eagainDE[seq_, cond_, iter_] :=
  model6origin[nm, seq, cond, iter, DifferentialEvolution]
model6eNM[seq_, cond_, iter_] := model6origin[nm6e, seq, cond, iter, NelderMead]
model6eagainNM[seq_, iter_] := model6origin[nm, seq, iter, NelderMead]

nm7 = {1, {x1 → 0.36657353606884746, x1b → 0.9665387139253007,
  x2 → 0.09163584702319359, x3 → 0.9916353759462034, x4 → 0.6665765777629866,
  x5 → 0.9916353759462035, x6 → 0.09163584702319352, xA2 → 1.0832711475699537,
  y6 → 0.09163584702319352, yA2 → 0.10000039567754677}};
model7origin[nm0_, seq_, cond_, iter_, meth_] :=
  {nm = NMinimize[{d[seq], cond3, cond6, x1 < x4 < x1b} ∪ cond,
    {{x1, x1 /. nm0[[2]], (x1 /. nm0[[2]]) + .000001}, {x1b, x1b /. nm0[[2]],
     (x1b /. nm0[[2]]) + .000001}, {x2, x2 /. nm0[[2]], (x2 /. nm0[[2]]) + .000001},
     {x3, x3 /. nm0[[2]], (x3 /. nm0[[2]]) + .000001}, {x4, x4 /. nm0[[2]],
     (x4 /. nm0[[2]]) + .000001}, {x5, x5 /. nm0[[2]], (x5 /. nm0[[2]]) + .000001},
     {x6, x6 /. nm0[[2]], (x6 /. nm0[[2]]) + .000001}, {y6, y6 /. nm0[[2]],
     (y6 /. nm0[[2]]) + .000001}, {xA2, xA2 /. nm0[[2]], (xA2 /. nm0[[2]]) + .000001},
     {yA2, yA2 /. nm0[[2]], (yA2 /. nm0[[2]]) + .000001}},
    MaxIterations → iter, Method → meth],
  draw[seq, nm[[2]]];}
model7[seq_, cond_, iter_] := model7origin[nm7, seq, cond, iter, Automatic]
model7again[seq_, cond_, iter_] := model7origin[nm, seq, cond, iter, Automatic]
model7DE[seq_, cond_, iter_] :=
  model7origin[nm7, seq, cond, iter, DifferentialEvolution]
model7againDE[seq_, cond_, iter_] :=
  model7origin[nm, seq, cond, iter, DifferentialEvolution]
model7NM[seq_, cond_, iter_] := model7origin[nm7, seq, cond, iter, NelderMead]
model7againNM[seq_, cond_, iter_] := model7origin[nm, seq, cond, iter, NelderMead]

```


For a 30°-60°-90° triangle,

```

d[xys_] := If[Length[xys] == 2,
  Sqrt[(xys[[1, 1]] - xys[[2, 1]])^2 + (xys[[1, 2]] - xys[[2, 2]])^2],
  d[xys[[{1, 2}]]] + d[Rest[xys]]]

u[θ_] := {Cos[θ], Sin[θ]}; dd[xy_, θ_] := xy.u[θ]; sqrt3 = Sqrt[3];

p1 = {x1, y1}; p1b = {x1b, y1b}; p2 = {x2, y2}; p3 = {x3, y3};
p4 = {x4, y4}; p5 = {x5, y5}; p6 = {x6, y6}; p7 = {x7, y7}; p8 = {x8, y8};

m1 = Tan[π/3]; m2 = Tan[π/6]; y1 = 0; y1b = 0; y2 = m2 * x2; y3 = -m1 (x3 - 1);
y4 = yA2; y5 = m2 (x5 - xA2) + yA2; yA3 = -m1 (x3 - 1); yA4 = m1 (x6 - xA2 + 1) + yA2

N[1/Sqrt[3]]

Sqrt[3] (1 + x6 - xA2) + yA2

0.57735

α = 30°; β = 60°

60°

AB = 0.5 / Sin[α];
A1 = {0, 0}; C1 = {1, 0}; B1 = AB u[α];
A2 = {xA2, yA2}; C2 = {xA2 - 1, yA2}; B2 = A2 + AB u[180° + α];
A3 = {xA3, yA3}; C3 = {xA3, yA3 - 1}; B3 = A3 + u[270° + α];
A4 = {xA4, yA4}; C3 = {xA4, yA4 + 1}; B4 = A4 + u[90° + α];

u[θ_] = {Cos[θ], Sin[θ]};
Cross3[{x1_, y1_}, {x2_, y2_}] = x1 y2 - x2 y1;
OnRight[R_, P_, Q_] = Cross3[R - P, Q - P] > 0;
cond3 = OnRight[p3, C1, B1];
cond6 = dd[p6 - A2, 210°] > Sqrt[3]/2;
cond7 = x7 < xA3;
cond8 = x8 > xA4;
condt1 = y4 < dd[p5 - p2, α - 90°];

```

```

draw[arc_, eval_] := Show[
  Graphics[{{RGBColor[0, 1, 0], Line[{{(0, 0), (1, 0), (1, 0) +  $\frac{1}{2}$  u[120°], (0, 0)}}]},
    {RGBColor[0, 0, 1], Line[{{xA2, yA2}, {xA2 - 1, yA2}, {xA2, yA2} +  $\frac{\sqrt{3}}{2}$  u[-150°],
      {xA2, yA2}}]}, {Thickness[.004], Line[arc]}] /. eval],
  AspectRatio → Automatic, PlotRange → {{-.5, 2}, {-.5, .6}}]

nm6 = {1, {x1 → 0.20463559160489397, x2 → 0.2795381017954675,
  x3 → 0.838609432980824, x4 → 0.838609432980824, x5 → 0.763708005476749,
  x6 → 0.2046355916015553, xA2 → 1.043245022547358,
  y6 → 6.62816961450422*^-11, yA2 → 0.27953666193956267}};

model6origin[nm0_, seq_, cond_, iter_, meth_] := {
  nm = NMinimize[{d[seq], cond3, cond6} ∪ cond,
    {{x1, x1 /. nm0[[2]], (x1 /. nm0[[2]]) + .000001},
    {x2, x2 /. nm0[[2]], (x2 /. nm0[[2]]) + .000001},
    {x3, x3 /. nm0[[2]], (x3 /. nm0[[2]]) + .000001}, {x4, x4 /. nm0[[2]],
    (x4 /. nm0[[2]]) + .000001}, {x5, x5 /. nm0[[2]], (x5 /. nm0[[2]]) + .000001},
    {x6, x6 /. nm0[[2]], (x6 /. nm0[[2]]) + .000001}, {y6, y6 /. nm0[[2]],
    (y6 /. nm0[[2]]) + .000001}, {xA2, xA2 /. nm0[[2]], (xA2 /. nm0[[2]]) + .000001},
    {yA2, yA2 /. nm0[[2]], (yA2 /. nm0[[2]]) + .000001}},
  MaxIterations → iter, Method → meth],
  draw[seq, nm[[2]]];}

model6[seq_, cond_, iter_] := model6origin[nm6, seq, cond, iter, Automatic]
model6again[seq_, cond_, iter_] := model6origin[nm, seq, cond, iter, Automatic]
model6DE[seq_, cond_, iter_] :=
  model6origin[nm6, seq, cond, iter, DifferentialEvolution]
model6againDE[seq_, cond_, iter_] :=
  model6origin[nm, seq, cond, iter, DifferentialEvolution]
model6NM[seq_, cond_, iter_] := model6origin[nm6, seq, cond, iter, NelderMead]
model6againNM[seq_, iter_] := model6origin[nm, seq, iter, NelderMead]

nm6e =
  {1, {x1 → .5, x2 → .3, x3 → .7, x4 → .5, x5 → .7, x6 → .2, y6 → .1, xA2 → 1, yA2 → .4}};
model6eorigin[nm0_, seq_, cond_, iter_, meth_] := {x4 = x1;
  nm = NMinimize[{d[seq], cond3, cond6} ∪ cond,
    {{x1, x1 /. nm0[[2]], (x1 /. nm0[[2]]) + .000001},
    {x2, x2 /. nm0[[2]], (x2 /. nm0[[2]]) + .000001},
    {x3, x3 /. nm0[[2]], (x3 /. nm0[[2]]) + .000001},
    {x5, x5 /. nm0[[2]], (x5 /. nm0[[2]]) + .000001}, {x6, x6 /. nm0[[2]],
    (x6 /. nm0[[2]]) + .000001}, {y6, y6 /. nm0[[2]], (y6 /. nm0[[2]]) + .000001},
    {xA2, xA2 /. nm0[[2]], (xA2 /. nm0[[2]]) + .000001}, {yA2, yA2 /. nm0[[2]],
    (yA2 /. nm0[[2]]) + .000001}}, MaxIterations → iter, Method → meth],
  draw[seq, nm[[2]]];, x4 =.}

model6e[seq_, cond_, iter_] := model6eorigin[nm6e, seq, cond, iter, Automatic]
model6eagain[seq_, cond_, iter_] := model6eorigin[nm, seq, cond, iter, Automatic]
model6eDE[seq_, cond_, iter_] :=
  model6eorigin[nm6e, seq, cond, iter, DifferentialEvolution]
model6eagainDE[seq_, cond_, iter_] :=
  model6eorigin[nm, seq, cond, iter, DifferentialEvolution]
model6eNM[seq_, cond_, iter_] := model6eorigin[nm6e, seq, cond, iter, NelderMead]
model6eagainNM[seq_, iter_] := model6eorigin[nm, seq, iter, NelderMead]

```

```

nm7 = {1, {x1 → 0.00015870181522523703, x1b → 0.998723667953158,
  x2 → 0.00012153457890932463, x3 → 1, x4 → 0.9987236557054678,
  x5 → 0.9999994803974714, x6 → 0.00015870181570898427, xA2 → 1.0001197031262972,
  y6 → -3.688713763988427*^-14, yA2 → 0.00006766302132861847}};
model7origin[nm_, seq_, cond_, iter_, meth_] :=
  {nm = NMinimize[{d[seq], cond3, cond6, x1 < x4 < x1b} ∪ cond,
    {{x1, x1 /. nm0[[2]], (x1 /. nm0[[2]]) + .000001}, {x1b, x1b /. nm0[[2]],
      (x1b /. nm0[[2]]) + .000001}, {x2, x2 /. nm0[[2]], (x2 /. nm0[[2]]) + .000001},
      {x3, x3 /. nm0[[2]], (x3 /. nm0[[2]]) + .000001}, {x4, x4 /. nm0[[2]],
        (x4 /. nm0[[2]]) + .000001}, {x5, x5 /. nm0[[2]], (x5 /. nm0[[2]]) + .000001},
        {x6, x6 /. nm0[[2]], (x6 /. nm0[[2]]) + .000001}, {y6, y6 /. nm0[[2]],
          (y6 /. nm0[[2]]) + .000001}, {xA2, xA2 /. nm0[[2]], (xA2 /. nm0[[2]]) + .000001},
          {yA2, yA2 /. nm0[[2]], (yA2 /. nm0[[2]]) + .000001}},
    MaxIterations → iter, Method → meth],
  draw[seq, nm[[2]]];}
model7[seq_, cond_, _iter_] := model7origin[nm7, seq, cond, iter, Automatic]
model7again[seq_, cond_, iter_] := model7origin[nm, seq, cond, iter, Automatic]
model7DE[seq_, cond_, iter_] :=
  model7origin[nm7, seq, cond, iter, DifferentialEvolution]
model7againDE[seq_, cond_, iter_] :=
  model7origin[nm, seq, cond, iter, DifferentialEvolution]
model7NM[seq_, cond_, iter_] := model7origin[nm7, seq, cond, iter, NelderMead]
model7againNM[seq_, iter_] := model7origin[nm, seq, iter, NelderMead]

```

VITA

Mr.Panuwat Tansatian was born on October 9th, 1982 in Nakornpathom Thailand. He graduated with a Bachelor of Science Degree in Mathematics from Mahidol University in 2005 (First Class Honor).

