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## APPENDIX

**Theorem 1.** Given a data set  $\mathbf{Y}$  used for parameter adjustment of a VEBF, assume that a data points  $\mathbf{y}_i \in \mathbf{Y}$  is uncovered by the closest  $j^{\text{th}}$  VEBF,  $\psi(\mathbf{y}_i; \bar{\mathbf{x}}^j, \mathbf{w}^j, \mathbf{U}^j)$ ,

If the width vector  $\mathbf{w}^j = [w_1^j \ w_2^j \ \dots \ w_n^j]^T$  is updated by  $\mathbf{w}_i^j = \varepsilon \mathbf{w}_i^j$ , where  $\varepsilon = \sqrt{1 + \eta * \max_{val}}$  and  $\eta \geq 1$ , then the data set  $\mathbf{Y}$  will eventually be covered by the VEBF  $\psi(\mathbf{y}_i; \bar{\mathbf{x}}^j, \mathbf{w}^j, \mathbf{U}^j)$ .

*Proof*

Let  $\eta \geq 1$  and  $\max_{val} = \max_{\mathbf{y}_i \in \mathbf{Y}} (\psi(\mathbf{y}_i, \bar{\mathbf{x}}^j, \mathbf{w}^j, \mathbf{U}^j))$

So,  $\forall \mathbf{y}_i \in \mathbf{Y}$ ,  $\psi(\mathbf{y}_i, \bar{\mathbf{x}}^j, \mathbf{w}^j, \mathbf{U}^j) \leq \max_{val}$

$$\sum_{l=1}^n \frac{((\mathbf{y}_i - \bar{\mathbf{x}}^j)^T \mathbf{u}_l^j)^2}{(w_l^j)^2} - 1 \leq \max_{val}$$

Since  $\eta \geq 1$ ,

$$\sum_{l=1}^n \frac{((\mathbf{y}_i - \bar{\mathbf{x}}^j)^T \mathbf{u}_l^j)^2}{(w_l^j)^2} - 1 \leq \eta * \max_{val}$$

$$\sum_{l=1}^n \frac{((\mathbf{y}_i - \bar{\mathbf{x}}^j)^T \mathbf{u}_l^j)^2}{(w_l^j \sqrt{1 + \eta * \max_{val}})^2} \leq 1$$

$$\sum_{l=1}^n \frac{((\mathbf{y}_i - \bar{\mathbf{x}}^j)^T \mathbf{u}_l^j)^2}{(w_l^j \sqrt{1 + \eta * \max_{val}})^2} - 1 \leq 0$$

$$\psi(\mathbf{y}_i, \bar{\mathbf{x}}^j, \varepsilon \mathbf{w}^j, \mathbf{U}^j) \leq 0, \text{ where } \varepsilon = \sqrt{1 + \eta * \max_{val}}.$$

By Definition 1, the data set  $\mathbf{Y}$  is covered if the width vector

is updated by  $\mathbf{w}^j = \varepsilon \mathbf{w}^j$  where  $\varepsilon = \sqrt{1 + \eta * \max_{val}}$ .

**Theorem 2.** Given a data chunk  $\wp$  with  $n$  samples, the time complexity  $T_{alg}$  of the Data-throwaway Learning Streaming Chunk (DLSC) algorithm is  $O(K + n^2)$ , where  $K$  the number of hidden neurons before presenting a data chunk  $\wp$ .

*Proof*

Given VEBFNN with  $K$  hidden neurons and a data chunk  $\wp$  with  $n$  samples,  $\wp = \{\{\mathbf{X}^j, t^j\}_{j=1}^p\}$  where  $\{\mathbf{X}^j, t^j\}$  is the set samples  $\mathbf{X}^j$  with the class label  $t^j$  and  $p$  is a small number. Let  $|\mathbf{X}^j|$  denote the number of samples belonging to class label  $t^j$  and  $\sum_{j=1}^p |\mathbf{X}^j| = n$ . At lines 1-4, since the computational time does not depend on the number of data, the time taken in these lines is constant and then, given by  $T_1 = O(1)$ .

For each category  $\{\mathbf{X}^j, t^j\}$ , if  $t^j$  is the new class label, then Lines 6-13 are performed. The time complexity is  $T_2 = O(1)$  at lines 6. In Do While loop at line 7, the worst case is considered. Because the learning time of *CreateNewNeuron* at line 8 does not depend on the number of data, the time complexity is  $O(1)$ . Thus, the time complexity of *CreateNewNeuron* for all data with  $p$  class label is  $T_3 = pO(1) = O(1)$ . Then, the *UpdateParameter* at line 10 is executed until  $\mathbf{X}^j$  is empty. The worst case is considered. The worst case appears when the size of each category  $\mathbf{X}^j$  is reduced by one at a time for parameter update in *UpdateParameter*. The function *UpdateParameter* contains a subfunction called *FormCoveredData*. There are four operations including three computations and one comparison within this subfunction. The computational time of each operation is constant. Since the size of the  $\mathbf{X}^j$  is reduced by one at a time for worst case, the computational time for each operation is given by

$$(|\mathbf{X}^j|) + (|\mathbf{X}^j| - 1) + (|\mathbf{X}^j| - 2) + \dots + 2 + 1 = \frac{1}{2}(|\mathbf{X}^j| + 1)|\mathbf{X}^j| \in O(|\mathbf{X}^j|^2).$$

Then, the time for  $\mathbf{X}^j$  is  $T_4 = 4 \times O(|\mathbf{X}^j|^2)$ . Within *UpdateParameter*, the worst case appears when only one datum is used for parameter update given by  $|\mathbf{Y}| = 1$ . Then, the time does not depend on the number of data. The time is  $O(|\mathbf{X}^j|)$ . The time of

*UpdateParameter* in Do-While loop is  $O(|\mathbf{X}^j|^2) + O(|\mathbf{X}^j|^2) = O(|\mathbf{X}^j|^2)$ . So, the time for new class label is  $T_2 + T_3 + T_4 = O(1) + O(1) + O(|\mathbf{X}^j|^2) = O(|\mathbf{X}^j|^2)$ .

If  $t^j$  is the old class label, then Lines 15-31 are performed. As the old class label, the worst case is considered. In Do-While loop at lines 15-23, the worst case appears when the data  $\mathbf{X}^j$  reduced by one for the data  $\mathbf{X}^j$ . The computational time at line 16 is  $T_5 = O(|\mathbf{X}^j|)$ . At line 17, the time is  $T_6 = O(K)$ . For merging process, the time of worst case is equal to  $T_7 = K + |\mathbf{X}^j| = O(K + |\mathbf{X}^j|)$ . In Do-While loop at lines 24-29, the time of worst case is  $T_8 = O(|\mathbf{X}^j|^2)$  as the old class label case.

Therefore, the time complexity of the DLSC algorithm for  $p$  classes is  $T_1$  + time for each new class + time for each old class  $\leq T_1 + p(T_2 + T_3 + T_4) + p(T_5 + T_6 + T_7 + T_8)$

$$\leq O(1) + \left( pO(1) + pO(1) + \sum_j^p O(|\mathbf{X}^j|^2) \right) + \left( \sum_{j=1}^p O(|\mathbf{X}^j|) + pO(K) + O(K + \sum_j^p |\mathbf{X}^j|) + O(\sum_j^p |\mathbf{X}^j|^2) \right) \in O(K + \sum_j^p |\mathbf{X}^j|^2) = O(K + n^2).$$



## VITA

Name: Mr. Prem Junsawang

Date of Birth: 28th February, 1982

Educations:

M.Sc. degree in Computational Science, Department of Mathematics, Faculty of Science, Chulalongkorn University, Bangkok, Thailand.

B.Sc. degree (honors) in Mathematics, Department of Mathematics, Faculty of Science, Khon Kaen University, Khon Kaen, Thailand.

Scholarship: Development and Promotion of Science and Technology Talents Project (DPST), the Institute for Promotion and Teaching Science and Technology (IPST), Ministry of Science and Technology.

