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Appendix

Bezier Spline Curves

Bezier curves is widely used in computer graphics and computer-aided design. The curve is not really interpolating splines that it does not normally pass through all of the points. However, Bezier curves has the important property of staying within the polygon determined by the given points. In addition, Bezier spline curves have a nice geometric property in that in changing one of the points we change only one portion of the curve called a local effect. Finally, for the cubic splines just studied the points were given data points. For the two curves we study in this thesis the points in question are more likely control points that we select to determine the shape of the curve that we are working on.

For simplicity, we consider mainly the cubic version of the Bezier curves. We will express y = f(x) in parametric form. The parametric form represents a relation between x and y by two other equations, $x = F_1(u)$, $y = F_2(u)$. The independent variable u is called the parameter. For example, the equation for a circle can be written with θ as the parameter as

$$x = r \cdot \cos(\theta), \tag{1}$$

$$y = r \cdot \sin(\theta). \tag{2}$$

When y and x are expressed in terms of a parameter u, (x(u), y(u)), $0 \le u \le 1$, defines a set of points (x, y), associated with the values of u.

Suppose we are given a set of control points, $p_i = (x_i, y_i)$, i = 0, 1, ..., n. (These points are also referred to as Bezier Points.) Figure A-1 is an example.

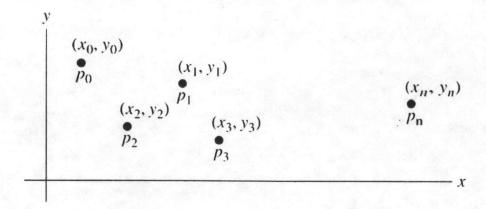


Figure A-1: Represent points on a 2D plane.

The points do not necessarily progress from left to right. We treat the coordinates of each point as a two-component vector,

$$p_i = \begin{pmatrix} x_i \\ y_i \end{pmatrix}. \tag{3}$$

The set of points, in parametric form, is

$$P(u) = \begin{pmatrix} X(u) \\ Y(u) \end{pmatrix}, \quad 0 \le u \le 1.$$
 (4)

The *m* th-degree Bezier polynomial determined by *n* points (where n = m + 1) is given by

$$P(u) = \sum_{i=0}^{m} {m \choose i} (1-u)^{m-i} u^{i} p_{i}, \text{ where}$$
 (5)

$$\binom{m}{i} = \frac{m!}{i!(m-i)!} \tag{6}$$

The preceding formula really represents two other scalar equations, one for X_i and the other for Y_i .

For n = 6, this would give the equation defined by six points p_0, p_1, p_2, p_3, p_4 , and p_5 :

$$P(u) = (1-u)^5 p_0 + 5(1-u)^4 u p_1 + 10(1-u)^3 u^2 p_2 + 10(1-u)^2 u^3 p_3 + 5(1-u)u^4 p_4 + u^5 p_5,$$

since, for
$$m = 5$$
 and $i = 0, 1, ..., 5$, we have $\binom{5}{0} = 1$, $\binom{5}{1} = 5$, $\binom{5}{2} = 10$, $\binom{5}{3} = 10$, $\binom{5}{4} = 5$,

and $\binom{5}{5} = 1$. The preceding equation represents the pair of equations

$$X(u) = (1-u)^5 x_0 + 5(1-u)^4 u x_1 + 10(1-u)^3 u^2 x_2 + 10(1-u)^2 u^3 x_3 + 5(1-u)u^4 x_4 + u^5 x_5,$$

$$Y(u) = (1-u)^5 y_0 + 5(1-u)^4 u y_1 + 10(1-u)^3 u^2 y_2 + 10(1-u)^2 u^3 y_3 + 5(1-u)u^4 y_4 + u^5 y_5.$$

Observe that, if u = 0 then X(0) is identical to x_0 and similarly for Y(0). If u = 1, the point referred to is (x_5, y_5) . As u takes on values between 0 and 1, a curve is traced that goes from the first point to the sixth point of the set. Ordinarily the curve will not pass through the central point of the six except if they are collinear then the curve is the straight line through them all. An example of the Bezier spline curve, which is constructed by six control points shows in Figure A-2.

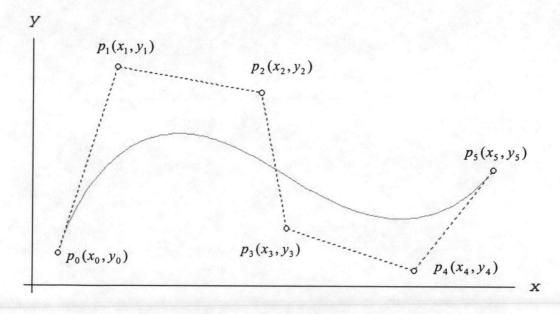


Figure A-2: An example of 5th degree of Bezier spline curve.

An algorithm for drawing a piece of a 5th degree of Bezier spline curve is shown below:

Algorithm of the 5th degree - Bezier Spline Curve

- 1. Given six control points, $p_i(x_i, y_i)$, i = 0, ..., 5
- 2. **FOR** u = 0 **TO** 1 STEP 0.01 **DO**
- 3. Compute
- 4. $X = (1-u)^5 x_0 + 5(1-u)^4 u x_1 + 10(1-u)^3 u^2 x_2 + 10(1-u)^2 u^3 x_3 + 5(1-u)u^4 x_4 + u^5 x_5$
- 5. $Y = (1-u)^5 y_0 + 5(1-u)^4 u y_1 + 10(1-u)^3 u^2 y_2 + 10(1-u)^2 u^3 y_3 + 5(1-u)u^4 y_4 + u^5 y_5$.
- 6. Plot (X,Y).
- 7. END FOR.

Vitae

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