

## CHAPTER III

### ROLLE'S THEOREM IN BANACH SPACES

In this chapter, we establish theorems, analogous with Rolle's theorem, for functions from a subset of  $\mathbf{R}^n$  into a real Banach space  $\mathbf{B}$ . And as a consequence we obtained a version of mean valued theorem.

**Theorem 3.1.** *Let  $f: D(x_0, r) \rightarrow \mathbf{B}$  be continuous on  $D(x_0, r)$  and Fréchet differentiable on  $B(x_0, r)$ . If there is a continuous linear functional  $\phi: \mathbf{B} \rightarrow \mathbf{R}$ , and a point  $z_0 \in B(x_0, r)$  such that  $\phi(f(x) - f(z_0))$  does not change sign on  $S(x_0, r)$ , then there exists a vector  $c \in B(x_0, r)$  such that*

$$\phi(df(c)(u)) = 0 \quad \text{for all } u \in \mathbf{R}^n.$$

**Proof.** Let  $\phi$  be a continuous linear functional on  $\mathbf{B}$  and  $z_0$  a point in  $B(x_0, r)$  such that  $\phi(f(x) - f(z_0))$  does not change sign on  $S(x_0, r)$ . Let  $g: D(x_0, r) \rightarrow \mathbf{R}$  be defined by  $g(x) = \phi(f(x))$  for each  $x \in D(x_0, r)$ . Then  $g$  is continuous on  $D(x_0, r)$  and differentiable on  $B(x_0, r)$ . Assume that  $\phi(f(x) - f(z_0)) \leq 0$  for all  $x \in S(x_0, r)$ . Then for any  $x$  in  $S(x_0, r)$ ,  $g(x) \leq g(z_0)$ . Since  $g$  is continuous on the compact set  $D(x_0, r)$ , then  $g$  attains its maximum on  $D(x_0, r)$ . That is, there is a point  $c \in B(x_0, r)$  such that  $g(c) = \max \{ g(x) \mid x \in D(x_0, r) \}$ . Thus  $dg(c) = 0$ , and hence  $\phi(df(c))(u) = d(\phi \circ f)(c)(u) = dg(c)(u) = 0$  for all  $u \in \mathbf{R}^n$ .

The proof for the case  $\phi(f(x) - f(z_0)) \geq 0$  for all  $x$  in  $S(x_0, r)$ , is similar ■

If the assumption in theorem 3.1 is slightly weakened by replacing the condition that there is  $z_0 \in B(x_0, r)$  such that  $\phi(f(x) - f(z_0))$  does not change sign on  $S(x_0, r)$  with the condition that

$$\phi(f(x)) = k, \text{ for each } x \text{ in } S(x_0, r), \text{ where } k \text{ is a constant}$$

then the conclusion is still the same.

**Theorem 3.2.** *Let  $f : D(x_0, r) \rightarrow \mathbf{B}$  be continuous on  $D(x_0, r)$  and Fréchet differentiable on  $B(x_0, r)$ . If  $\phi : \mathbf{B} \rightarrow \mathbf{R}$  is a continuous linear functional such that  $\phi(f(x))$  is constant on  $S(x_0, r)$  then there is a vector  $c$  in  $B(x_0, r)$  such that*

$$\phi(df(c)(u)) = 0 \quad \text{for all } u \in \mathbf{R}^n.$$

**Proof.** Let  $\phi : \mathbf{B} \rightarrow \mathbf{R}$  be a continuous linear functional such that

$$\phi(f(x)) = k \quad \text{for all } x \in S(x_0, r), \text{ where } k \text{ is a constant}$$

Then  $\phi(f(x) - f(x_0)) = \phi(f(x)) - \phi(f(x_0)) = k - \phi(f(x_0))$  for all  $x \in S(x_0, r)$ .

Therefore the map  $x \mapsto \phi(f(x) - f(x_0))$  is a constant map on  $S(x_0, r)$ . By theorem 3.1, there exists a point  $c \in B(x_0, r)$  such that

$$\phi(df(c)(u)) = 0 \quad \text{for all } u \in \mathbf{R}^n. \quad \blacksquare$$

Theorem 3.1. and theorem 3.2. are not necessarily true when the space  $\mathbf{R}^n$  is replaced by an infinite dimensional Banach space, as illustrated by the following example.

**Example.** ([2]) Let  $L$  and  $R$  denote the continuous linear operators in  $l_2$  given by

$$L(x) = (x_2, x_3, \dots),$$

$$R(x) = (0, x_1, x_2, x_3, \dots), \text{ for } x = (x_1, x_2, x_3, \dots) \in l_2.$$

Let  $T$  be the map  $T: l_2 \rightarrow l_2$  defined as

$$T(x) = ((1/2) - \|x\|^2) e_1 + R(x), \text{ where } e_1 = (1, 0, 0, \dots), \text{ for } x \in l_2.$$

Define the function  $f: l_2 \rightarrow \mathbf{R}$  by

$$f(x) = \frac{1 - \|x\|^2}{\|x - T(x)\|^2}, \text{ for } x \in l_2.$$

Since the map  $T$  has no fixed point,  $\|x - T(x)\| \neq 0$  for any  $x \in l_2$  and  $f$  is well defined. Then  $f$  is continuous in  $l_2$  and  $f(x) = 0$  for every  $x \in S(0, 1)$ . As shown in the example in chapter II, the Fréchet derivative of  $g$  where  $g(x) = \|x\|^2$  at  $x \in l_2$  is the continuous linear function  $dg(x): u \mapsto 2\langle x, u \rangle$ . So,  $T$  is Fréchet differentiable at  $x$  and, for each  $u \in l_2$ ,

$$dT(x)(u) = -2\langle x, u \rangle e_1 + R(u).$$

Hence the Fréchet derivative of  $h$  where  $h(x) = \|x - T(x)\|^2$  at  $x \in l_2$  is the continuous linear function  $dT(x): u \mapsto 2\langle x - T(x), u - dT(x)(u) \rangle$  for each  $u \in l_2$ .

Then by the corollary 2.9,  $f$  is Fréchet differentiable at every  $x \in l_2$  and,

for each  $u \in l_2$ ,

$$df(x)u = \frac{1}{\|x - T(x)\|^4} \times [-2\|x - T(x)\|^2 \langle x, u \rangle - 2(1 - \|x\|^2) \langle x - T(x), u - dT(x)u \rangle].$$

Since  $\langle T(x), e_1 \rangle = \frac{1}{2} - \|x\|^2$  and  $\langle x, Ru \rangle = \langle Lx, u \rangle$ ,  $L(T(x)) = x$ , it follow that

$$\langle x - T(x), u - dT(x)u \rangle = \langle (1 + 2x_1 + 2\|x\|^2)x - T(x) - L(x), u \rangle.$$

Therefore,

$$df(x)u = \frac{-2}{\|x - T(x)\|^4} \\ \times \langle \|x - T(x)\|^2 + (1 - \|x\|^2)(1 + 2x_1 + 2\|x\|^2)x - (1 - \|x\|^2)(L(x) + T(x)), u \rangle.$$

For each  $x$  in  $I_2$ , let

$$F(x) = \frac{-2}{\|x - T(x)\|^4} \times [ \|x - T(x)\|^2 + (1 - \|x\|^2)(1 + 2x_1 + 2\|x\|^2)x - (1 - \|x\|^2)(L(x) + T(x)) ].$$

Then  $df(x)(u) = \langle F(x), u \rangle$  for all  $u \in I_2$ ,

We note that if  $df(x)(u) = 0$  for all  $u \in I_2$ , then  $F(x) = 0$  for all  $u \in I_2$ .

Next, we show that there exists no  $x$  in  $B(0,1)$  such that  $df(x) = 0$ .

Suppose that  $df(x) = 0$ , for some  $x \in B(0,1)$ . Since  $\frac{-2}{\|x - T(x)\|^4} \neq 0$ , then

$$[ \|x - T(x)\|^2 + (1 - \|x\|^2)(1 + 2x_1 + 2\|x\|^2)x - (1 - \|x\|^2)(L(x) + T(x)) ] = 0.$$

That is,  $(\frac{\|x - T(x)\|^2}{1 - \|x\|^2} + 1 + 2x_1 + 2\|x\|^2)x = L(x) + T(x)$ .

$$\text{Let } s = \frac{\|x - T(x)\|^2}{1 - \|x\|^2} + 1 + 2x_1 + 2\|x\|^2. \quad \dots\dots\dots (1)$$

Then  $L(x) + T(x) = sx$  and  $L^2(x) - sL(x) + x = 0$ . So, for each  $n \geq 1$ ,

$$x_{n+2} = sx_{n+1} - x_n.$$

That is,  $x \in \text{Ker}(L^2 - sL + I)$  is a recurrent sequence of order two in  $I_2$ . The associated characteristic equation for this type of sequence is

$$t^2 - st + 1 = 0. \dots\dots\dots(2)$$

This equation gives us three different alternatives according to the sign of its discriminant. That is,  $|s| = 2$ ,  $|s| < 2$  and  $|s| > 2$ .

Case 1.  $|s| = 2$ .

For each  $n \geq 1$ ,

$$x_n = A \left(\frac{s}{2}\right)^n + B(n) \left(\frac{s}{2}\right)^n, \text{ for some real numbers } A, B.$$

Since  $(x_n) \in I_2$ ,  $\lim_{n \rightarrow \infty} x_n = 0$ , so we have that  $A = B = 0$ , i.e,  $x = 0$ .

Since  $F(0) = 16e_1$ , then  $df(0)(u) = \langle F(0), u \rangle = \langle 16e_1, u \rangle = 16u_1$  for all  $u \in I_2$ ,

and this is a contradiction.

Case 2.  $|s| < 2$ .

Then the characteristic equation has two complex roots given by

$$\alpha = \cos\theta + i \sin\theta, \beta = \cos\theta - i \sin\theta, \sin\theta \neq 0.$$

Then, for each  $n \geq 1$ ,

$$\begin{aligned} x_n &= A(\cos\theta + i \sin\theta)^n + B(\cos\theta - i \sin\theta)^n . \\ &= (A+B)\cos n\theta + (A-B)i \sin n\theta . \end{aligned}$$

So  $x_n = C \cos n\theta + D \sin n\theta$  where  $C = A + B$ ,  $D = (A - B)i$ .

Since  $\sin\theta \neq 0$ , then if  $C$  or  $D$  is nonzero, then the sequence  $(x_n)$  has no limit. But  $\lim_{n \rightarrow \infty} x_n = 0$ , then  $C = D = 0$ . That is,  $x = 0$ . As in the case  $|s| = 2$ ,

this is a contradiction.

Case 3.  $|s| > 2$ . We have two real roots

$$\alpha = \frac{s + \sqrt{s^2 - 4}}{2}, \beta = \frac{s - \sqrt{s^2 - 4}}{2}.$$

We note that one of these roots has absolute value greater than one and the other less than one. Assume that  $|\alpha| > 1$  and  $|\beta| < 1$ . Again, we have a solution of (2) is

$$x_n = A\alpha^n + B\beta^n, \quad \text{for each } n \geq 1.$$

Since  $\lim_{n \rightarrow \infty} x_n = 0$ , we have  $A = 0$ . Then  $x_n = B\beta^{n-1}$ , for each  $n \geq 1$ .

So  $x = (x_1, x_1\beta, x_1\beta^2, \dots)$ ,  $\|x\|^2 = x_1^2 \left( \frac{1}{1-\beta^2} \right)$ , and

$$\begin{aligned} \|x - T(x)\|^2 &= \left\| \left( x_1 - \left( \frac{1}{2} - \frac{x_1^2}{1-\beta^2} \right), x_1\beta - x_1, x_1\beta^2 - x_1\beta, \dots \right) \right\|^2 \\ &= \left\| \left( x_1 + \frac{x_1^2}{1-\beta^2} - \frac{1}{2}, x_1(\beta - 1), x_1\beta(\beta - 1), \dots \right) \right\|^2 \\ &= \left( x_1 + \frac{x_1^2}{1-\beta^2} - \frac{1}{2} \right)^2 + \frac{x_1^2(1-\beta)}{1+\beta}. \end{aligned}$$

Since  $\beta^2 - s\beta + 1 = 0$ , then  $s = \left( \beta + \frac{1}{\beta} \right)$ .

From  $sx = T(x) + L(x)$ , we have  $sx_1 = \left( \frac{1}{2} \right) - \|x\|^2 + x_1\beta$ .

Therefore

$$x_1^2 + \frac{1-\beta^2}{\beta} x_1 - \frac{1}{2}(1-\beta^2) = 0. \quad \dots\dots\dots (3)$$

Since (3) implies

$$x_1^2 - \frac{1}{2}(1-\beta^2) = -\left( \frac{1-\beta^2}{\beta} \right) x_1, \text{ then}$$

$$\begin{aligned}
\|x - T(x)\|^2 &= \left( \frac{x_1(1-\beta^2) + x_1^2 - \frac{1}{2}(1-\beta^2)}{1-\beta^2} \right)^2 + \frac{x_1^2(1-\beta)^2}{1-\beta^2} \\
&= \left( \frac{x_1(1-\beta^2) + \frac{(1-\beta^2)}{\beta}x_1}{1-\beta^2} \right)^2 + \frac{x_1^2(1-\beta)^2}{1-\beta^2} \\
&= \left( x_1 - \frac{x_1}{\beta} \right)^2 + \frac{x_1^2(1-\beta)^2}{1-\beta^2} \\
&= x_1^2 \left[ \left( 1 - \frac{1}{\beta} \right)^2 + \left( \frac{1-\beta}{1+\beta} \right)^2 \right] \\
&= x_1^2 \left[ \left( \frac{\beta-1}{\beta} \right)^2 + \left( \frac{1-\beta}{1+\beta} \right)^2 \right] \\
&= x_1^2 \left[ \frac{(1-\beta)^2(1+\beta) + \beta^2(1-\beta)}{\beta^2(1+\beta)} \right] \\
&= \frac{x_1^2(1-\beta)}{\beta^2(1+\beta)} [(1-\beta^2) + \beta^2] \\
&= \frac{x_1^2(1-\beta)}{\beta^2(1+\beta)}.
\end{aligned}$$

From (3), we have  $x_1^2 = \frac{(1-\beta^2)(\beta-2x_1)}{2\beta}$  and  $\frac{2x_1^2}{1-\beta^2} = \frac{\beta-2x_1}{\beta}$ .

Hence, by substituting in (1), we have

$$\beta + \frac{1}{\beta} = \frac{x_1^2(1-\beta)}{\beta^2(1+\beta)} \cdot \frac{1-\beta^2}{1-\beta^2-x_1^2} + 1 + 2x_1 + \frac{2x_1^2}{1-\beta^2},$$

so

$$\begin{aligned}
 1 &= \frac{x_1^2(1-\beta)^2}{\beta(1-\beta^2-x_1^2)} + \beta + 2x_1\beta + (\beta-2x_1) - \beta^2 \\
 1 &= \frac{x_1^2(1-\beta)^2}{\beta(1-\beta^2-x_1^2)} + (\beta-2x_1)(1-\beta) + \beta \\
 1 &= \frac{(1-\beta^2)(\beta-2x_1)(1-\beta)^2}{2\beta^2(1-\beta^2-x_1^2)} + (\beta-2x_1)(1-\beta) + \beta \\
 1-\beta &= \frac{(1-\beta^2)(\beta-2x_1)(1-\beta)^2}{2\beta^2(1-\beta^2-x_1^2)} + (\beta-2x_1)(1-\beta) \\
 1 &= (\beta-2x_1) + \frac{(1-\beta^2)(\beta-2x_1)(1-\beta)}{2\beta^2(1-\beta^2-x_1^2)} \\
 1 &= (\beta-2x_1) + \left[ \frac{(1-\beta^2)(1-\beta)}{2\beta^2(1-\beta^2-x_1^2)} \right] \dots\dots\dots(4)
 \end{aligned}$$

From (3), we consider two subcases :

Subcase 3.1.  $x_1 = \frac{-1+\beta^2-\sqrt{1-\beta^2}}{2\beta}$

Since  $\|x\| < 1$ ,  $1-\beta^2 > x^2$ . i.e,  $x_1^2 + \beta^2 < 1$ .

From (4), we have that  $0 < \beta - 2x_1 < 1$ . Then

$$\beta - 2x_1 = \beta - 2\left(\frac{-1+\beta^2-\sqrt{1-\beta^2}}{2\beta}\right) = \frac{1+\sqrt{1-\beta^2}}{\beta}$$

so  $0 < \frac{1+\sqrt{1-\beta^2}}{\beta} < 1$ . Thus  $\beta > 1 + \sqrt{1-\beta^2} > 1$ .

A contradiction, since  $|\beta| < 1$ .



Subcase 3.2.  $x_1 = \frac{-1 + \beta^2 + \sqrt{1 - \beta^4}}{2\beta}$

Note that  $1 - x_1^2 - \beta^2 = 1 - \left( \frac{-1 + \beta^2 + \sqrt{1 - \beta^4}}{2\beta} \right)^2 - \beta^2$

$$= (1 - \beta^2) - \left( \frac{1}{2\beta} \right) (1 - \beta^2) \left[ \frac{1 - \beta^2 + 1 + \beta^2 - 2\sqrt{1 - \beta^4}}{2\beta} \right]$$

$$= \frac{1}{2\beta} (1 - \beta^2) \left[ \beta + \frac{2(-1 + \beta^2 + \sqrt{1 - \beta^4})}{2\beta} \right]$$

$$= \frac{1}{2\beta} (1 - \beta^2)(\beta + 2x_1).$$

From (4), we have that

$$1 = \frac{1}{\beta} (1 - \sqrt{1 - \beta^4}) \frac{2\beta^2 - \beta + \sqrt{1 - \beta^4}}{2\beta^2 - 1 + \sqrt{1 - \beta^4}}$$

$$\beta(2\beta^2 - 1 + \sqrt{1 - \beta^4}) = (1 - \sqrt{1 - \beta^4})(2\beta^2 - \beta + \sqrt{1 - \beta^4})$$

$$2\beta^3 = (1 - \sqrt{1 - \beta^4})(2\beta^2 - \beta + \sqrt{1 - \beta^4}) + \beta(1 - \sqrt{1 - \beta^4})$$

$$2\beta^3 = (1 - \sqrt{1 - \beta^4})(2\beta^2 + \sqrt{1 - \beta^4})$$

$$2\beta^3(1 + \sqrt{1 - \beta^4}) = \beta^4(2\beta^2 + \sqrt{1 - \beta^4})$$

$$2(1 + \sqrt{1 - \beta^4}) = \beta(2\beta + \sqrt{1 - \beta^4})$$

$$2 + 2\sqrt{1 - \beta^4} = 2\beta^3 + \beta\sqrt{1 - \beta^4}$$

$$2(1 - \beta^3) = (\beta - 2)\sqrt{1 - \beta^4}.$$

This is also a contradiction, since  $2(1 - \beta^3) > 0$  but  $(\beta - 2)\sqrt{1 - \beta^4} < 0$ .

With  $\phi =$  the identity function on  $\mathbf{R}$ , and  $z_0$  be any point in  $B(0,1)$ , we have for each  $x$  in  $S(0,1)$ ,  $\phi(f(x)) = f(x) = 0$  and  $\phi(f(x) - f(z_0)) = f(x) - f(z_0) = -f(z_0)$  in  $S(0,1)$  but there is no point  $x$  in  $B(0,1)$  such that  $df(x) = 0$  on  $I_2$ .

The following results are directly obtained when replace  $D(x_0, r)$  by the closure of any open bounded set of  $\mathbf{R}^n$  in Theorem 3.1 and Theorem 3.2.

For a subset  $A$  of  $\mathbf{R}^n$ , let  $\overline{A}$  and  $\partial A$  denote the closure of  $A$  and the boundary of  $A$ , respectively. We have the following theorem.

**Theorem 3.3.** *Let  $A$  be any open and bounded subset of  $\mathbf{R}^n$ ,  $f: \overline{A} \rightarrow B$  be continuous on  $\overline{A}$  and Fréchet differentiable on  $A$ . Let  $\phi: B \rightarrow \mathbf{R}$  be a continuous linear functional and let  $z_0$  be an element in  $A$  such that  $\phi(f(x) - f(z_0))$  does not change sign for all  $x \in \partial A$ . Then there exists  $c \in A$  such that*

$$\phi(df(c)(u)) = 0 \quad \text{for all } u \in \mathbf{R}^n.$$

**Proof.** Since  $\overline{A}$  is a compact, then the proof is similar to that of theorem 3.1 with  $D(x_0, r)$  is replaced by  $\overline{A}$ . ■

And also we have the following corollary.

**Corollary 3.4.** *Let  $f: \overline{A} \rightarrow \mathbf{B}$  be continuous on  $\overline{A}$  and Fréchet differentiable on  $A$ . Assume that there exists a continuous linear functional  $\phi: \mathbf{B} \rightarrow \mathbf{R}$  such that  $\phi(f(x))$  is constant for all  $x \in \partial A$ . Then there exists  $c \in A$  such that*

$$\phi(df(c)(u)) = 0 \quad \text{for all } u \in \mathbf{R}^n.$$

Rolle's theorem can be proved by using corollary 3.4.

**Corollary 3.5.** ( Rolle's Theorem )

*Let  $f: [a, b] \rightarrow \mathbf{R}$  be continuous on  $[a, b]$  and differentiable on  $(a, b)$ . If  $f(a) = f(b)$  then there is a point  $c \in (a, b)$  such that  $df(c) = 0$ .*

**Proof.** Assume that  $f(a) = f(b)$ . Let  $\phi: \mathbf{R} \rightarrow \mathbf{R}$  by  $\phi(x) = x$ . Then  $\phi$  is a continuous linear functional such that  $\phi(f(a)) = f(a) = f(b) = \phi(f(b))$ . By corollary 3.4, there is  $c \in (a, b)$  such that  $\phi(df(c)(u)) = 0$  for all  $u \in \mathbf{R}$ . Then  $\phi(df(c)(u)) = df(c)(u) = 0$  for all  $u \in \mathbf{R}$ , so  $df(c) = 0$ . ■

In 1996, Yamsakulna [7] proved Rolle's Theorem in Hilbert space. The corollary 3.7 is Yamsakulna's Rolle's Theorem. It can be obtained immediatly from theorem 3.2 as shown below.

**Corollary 3.6.** *Let  $\mathbf{H}$  be a Hilbert space. Let  $f : D(x_o, r) \rightarrow \mathbf{H}$  be continuous on  $D(x_o, r)$  and differentiable on  $B(x_o, r)$ . Assume that there exists a vector  $v \in \mathbf{H}$  such that  $\langle v, f(x) \rangle$  is constant on  $S(x_o, r)$ . Then there exists a vector  $c \in B(x_o, r)$  such that  $\langle v, df(c)(u) \rangle = 0$  for all  $u \in \mathbf{R}^n$ .*

**Proof.** Let  $v \in \mathbf{H}$  be such that  $g(x) = \langle v, f(x) \rangle$  is constant on  $S(x_o, r)$ . Let  $\phi : \mathbf{H} \rightarrow \mathbf{R}$  by  $\phi(x) = \langle v, x \rangle$ . Then  $\phi$  is continuous linear functional and  $\phi(f(x)) = \langle v, f(x) \rangle$  is constant in  $S(x_o, r)$ . By theorem 3.2, there exists  $c \in B(x_o, r)$  such that  $\phi(df(c)(u)) = 0$  for all  $u \in \mathbf{R}^n$ . Thus

$$\langle v, df(c)(u) \rangle = \phi(df(c)(u)) = 0 \text{ for all } u \in \mathbf{R}^n. \quad \blacksquare$$

The next corollary is the Rolle's theorem of Furi and Martelli [4], mentioned in the chapter I

**Corollary 3.7.** *Let  $f : D(x_o, r) \rightarrow \mathbf{R}^p$  be continuous on  $D(x_o, r)$  and differentiable on  $B(x_o, r)$ . Assume that there exists a vector  $v \in \mathbf{R}^p$  such that  $v \cdot f(x)$  is constant on  $S(x_o, r)$ . Thus there exists a vector  $c \in B(x_o, r)$  such that*

$$v \cdot df(c)(u) = 0 \quad \text{for every } u \in \mathbf{R}^n.$$

As a consequence of theorem 3.2 we have a theorem analogous to Sanderson's Mean Value Theorem.

**Theorem 3.8.** *Let  $a < b$  and  $f: [a, b] \rightarrow \mathbf{B}$  be  $k$  times Fréchet differentiable. Assume that there exists a continuous linear functional  $\phi: \mathbf{B} \rightarrow \mathbf{R}$  such that  $(\phi \circ f)(a) = (\phi \circ f)(b) = 0$  and the first  $k-1$  derivatives of  $f$  at  $a$  and  $\phi \circ d^{k-1}f(a)$  are 0. Then for some  $c \in (a, b)$ ,  $\phi \circ d^k f(c) = 0$ .*

**Proof.** By theorem 3.2, there exists  $c_1 \in (a, b)$  such that  $\phi \circ df(c_1) = 0$ . The theorem 3.2 can be applied to  $df$  in the interval  $[a, c_1]$ , so there exists  $c_2 \in (a, c_1)$  such that  $\phi \circ d(df)(c_2) = 0$ . i.e.  $\phi \circ d^2 f(c_2) = 0$ . Again, we apply the theorem 3.2 to  $d^2 f$  in the interval  $[a, c_2]$ , so there exists  $c_3 \in (a, c_2)$  such that  $\phi \circ d^3 f(c_3) = 0$ . This procedure can be repeated  $k-1$  times to obtain  $c = c_k \in (a, c_{k-1}) \subseteq (a, b)$  such that  $\phi \circ d^k f(c) = 0$ . ■

The next theorem is the Mean Value Theorem of Sanderson [6]. We show here that the theorem can be easily proved by using the theorem 3.8.

**Theorem 3.9.** (Sanderson's Mean Value theorem)

*Suppose  $f: [a, b] \rightarrow \mathbf{R}^n$  is a  $k$  times differentiable  $n$ -dimensional vector-valued function and  $f(a)$ ,  $f(b)$  and the first  $k-1$  derivatives of  $f$  at  $a$  are orthogonal to a non-zero vector  $v_0$ . Then for some  $c$  between  $a$  and  $b$ ,  $v_0$  is orthogonal to  $d^k f(c)$ .*

**Proof.** Let  $\phi: \mathbf{R}^n \rightarrow \mathbf{R}$  by  $\phi(x) = x \cdot v_0$  for each  $x \in \mathbf{R}^n$ . Then  $\phi$  is continuous linear functional and  $\phi(f(a)) = f(a) \cdot v_0 = 0 = f(b) \cdot v_0 = \phi(f(b))$ .

By theorem 3.8., there exists  $c \in (a, b)$  such that  $\phi \circ d^k f(c) = 0$ . Thus

$$d^k f(c)(u) \cdot v_0 = (\phi \circ d^k f(c))(u) = 0, \text{ for all } u \in \mathbf{R}^n.$$

So  $v_0$  is orthogonal to  $d^k f(c)$ . ■