

References



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Appendices

Appendix A:

Feynman's Average

The mean value of the functional $t_\Omega^d[x] = \int_0^t dt' \Theta_\Omega[x(t')]$, where $\Theta_\Omega[x(t')] = 1$ for $a \leq x \leq b$ and 0 otherwise, is given by

$$\bar{\tau}_D = \langle \Psi_f | t_\Omega^d | \Psi_i \rangle \quad (1)$$

or

$$\bar{\tau}_D = \frac{\int dx_2 \int dx_1 \Psi_f^*(x_2) \int D[x(t)] t_\Omega^d[x] \exp\left[\frac{i}{\hbar} S[x(t)]\right] \Psi_i(x_1)}{\int dx_2 \int dx_1 \Psi_f^*(x_2) \int D[x(t)] \exp\left[\frac{i}{\hbar} S[x(t)]\right] \Psi_i(x_1)}. \quad (2)$$

In particular case, the final state Ψ_f is obtained from Ψ_i by the evolution:

$$\begin{aligned} \Psi_f(x_2, t_2) &= \int dx_1 \langle x_2 | \mathbf{U}(t, 0) | x_1 \rangle \langle x_1 | \Psi_i \rangle \\ &= \int dx_1 \int D[x(t)] \exp\left\{\frac{i}{\hbar} S[x(t)]\right\} \Psi_i(x_1, t_1 = 0). \end{aligned} \quad (3)$$

so that we have

$$\int dx_2 \int dx_1 \Psi_f^*(x_2) \int D[x(t)] \exp\left[\frac{i}{\hbar} S[x(t)]\right] \Psi_i(x_1) = |\Psi_i|^2 = 1.$$

We have assumed that the initial state is normalized.

Now we consider

$$\begin{aligned} \int D[x(t)] t_\Omega^d \exp\left[\frac{i}{\hbar} S[x(t)]\right] &= \int_0^t dt' \int D[x(t)] \Theta_\Omega[x(t')] \exp\left[\frac{i}{\hbar} S[x(t')]\right] \\ &= \int_0^t dt' \int_\Omega dx K(x_2, x; t, t') K(x, x_1; t', 0). \end{aligned} \quad (4)$$

where $K(x, x_1; t', 0)$ is the propagator for the particle moving from x_1 at $t = 0$ to x_2 at t' and $K(x_2, x; t, t')$ is the propagator for the particle moving from x at t' to x_2 at t . Thus Eq.(1) can be written as

$$\begin{aligned} \bar{\tau}_D &= \langle \Psi_f | t_\Omega^d[x] | \Psi_i \rangle \\ &= \int_0^t dt' \int_\Omega dx \left[\int dx_2 \Psi_f^*(x_2) K(x_2, x; t, t') \right] \times \left[\int dx_1 \Psi_i(x_1) K(x, x_1; t', 0) \right]. \end{aligned} \quad (5)$$

By using the relation

$$\begin{aligned}
 \int dx_2 \Psi_f^*(x_2) K(x_2, x; t, t') &= \int dx_2 \langle \Psi_i | \mathbf{U}^\dagger(t, 0) | x_2 \rangle \langle x_2 | \mathbf{U}(t, t') | x \rangle \\
 &= \langle \Psi_i | \mathbf{U}^\dagger(t, 0) \mathbf{U}(t, t') | x \rangle \\
 &= \langle \Psi_i | \mathbf{U}^\dagger(t', 0) | x \rangle \\
 &= \Psi^*(x, t')
 \end{aligned} \tag{6}$$

and

$$\Psi(x, t') = \int dx_1 \Psi_i(x_1) K(x, x_1; t', 0), \tag{7}$$

we obtain the Feynman average of the functional $t_\Omega^{cl}[x]$ in the form

$$\bar{\tau}_D = \int_0^t dt' \int_\Omega dx |\Psi(x, t')|^2. \tag{8}$$

Appendix B:

A Theorem of Differential Calculus

A theorem of differential calculus is used. Let $\Phi(\lambda) = \int_{v(\lambda)}^{u(\lambda)} dx f(x, \lambda)$ where $u(\lambda)$ and $v(\lambda)$ are differentiable functions in a closed interval $[\lambda_0, \lambda_1]$; $f(x, \lambda)$ and $f'(x, \lambda)$ are continuous in the region $\lambda_0 \leq \lambda \leq \lambda_1$, then

$$\frac{\partial}{\partial \lambda} \Phi(\lambda) = \frac{\partial u}{\partial \lambda} f(x, u) - \frac{\partial v}{\partial \lambda} f(x, v) + \int_{v(\lambda)}^{u(\lambda)} dx \frac{\partial}{\partial \lambda} f(x, \lambda). \quad (1)$$

We prove the above theorem of differential calculus by considering the integral

$$\Phi(\lambda) \equiv \Phi(u(\lambda), v(\lambda), \lambda) = \int_{v(\lambda)}^{u(\lambda)} dx f(x, \lambda) = F(x, \lambda) \Big|_{v(\lambda)}^{u(\lambda)} = F(u(\lambda), \lambda) - F(v(\lambda), \lambda). \quad (2)$$

The partial differentives of $F(u, v, \lambda)$ with respect to u and v are

$$\frac{\partial}{\partial u} \Phi(u, v, \lambda) = \frac{\partial}{\partial u} F(u(\lambda), \lambda) = f(x, \lambda)_{u=x}, \quad (3)$$

$$\frac{\partial}{\partial v} \Phi(u, v, \lambda) = \frac{\partial}{\partial v} F(v(\lambda), \lambda) = f(x, \lambda)_{v=x}. \quad (4)$$

We consider the partial differential $\frac{\partial}{\partial \lambda} \Phi(\lambda)$:

$$\frac{\partial}{\partial \lambda} \Phi(\lambda) = \frac{\partial}{\partial \lambda} F(u(\lambda), \lambda) - \frac{\partial}{\partial \lambda} F(v(\lambda), \lambda) + \frac{\partial}{\partial \lambda} (F(u(\lambda), \lambda) - F(v(\lambda), \lambda))_{u,v}. \quad (5)$$

and

$$\frac{\partial}{\partial \lambda} F(u(\lambda), \lambda) = \frac{\partial u(\lambda)}{\partial \lambda} \frac{\partial}{\partial u} F(u(\lambda), \lambda). \quad (6)$$

$$\frac{\partial}{\partial \lambda} F(v(\lambda), \lambda) = \frac{\partial v(\lambda)}{\partial \lambda} \frac{\partial}{\partial v} F(v(\lambda), \lambda). \quad (7)$$

We substitute Eq.(6) and Eq.(7) into Eq.(5) to obtain

$$\frac{\partial}{\partial \lambda} \Phi(\lambda) = \frac{\partial u(\lambda)}{\partial \lambda} f(x, \lambda)_{u=x} - \frac{\partial v(\lambda)}{\partial \lambda} f(x, \lambda)_{v=x} + \frac{\partial}{\partial \lambda} (F(u(\lambda), \lambda) - F(v(\lambda), \lambda))_{u,v}. \quad (8)$$

By using the relation

$$\frac{\partial}{\partial \lambda} (F(u(\lambda), \lambda) - F(v(\lambda), \lambda))_{u,v} = \frac{\partial}{\partial \lambda} \Phi(u, v, \lambda) = \int_{v(\lambda)}^{u(\lambda)} dx \frac{\partial}{\partial \lambda} f(x, \lambda). \quad (9)$$

Eq.(8) becomes

$$\frac{\partial}{\partial \lambda} \Phi(\lambda) = \frac{\partial u(\lambda)}{\partial \lambda} f(x, \lambda)_{u=x} - \frac{\partial v(\lambda)}{\partial \lambda} f(x, \lambda)_{v=x} + \int_{v(\lambda)}^{u(\lambda)} dx \frac{\partial}{\partial \lambda} f(x, \lambda). \quad (10)$$

This is the theorem of differential calculus.

For an example, we want to use the theorem of differential calculus to find the partial derivative of a function $\Phi(\lambda)$, which is defined as

$$\Phi(\lambda) = \int_{\lambda}^{\lambda^2} dx (ax + \lambda). \quad (11)$$

Let us consider the function $\Phi(\lambda)$.

$$\Phi(\lambda) = \int_{\lambda}^{\lambda^2} dx (ax + \lambda) = \left(\frac{a}{2} (\lambda^2)^2 + \lambda (\lambda^2) \right) - \left(\frac{a}{2} (\lambda)^2 + \lambda (\lambda) \right). \quad (12)$$

or

$$\Phi(\lambda) = \frac{a}{2} \lambda^4 + \lambda^3 - \left(\frac{a}{2} - 1 \right) \lambda^2.$$

By straightforward substitution, we find the partial differential $\frac{\partial}{\partial \lambda} \Phi(\lambda)$ and we can obtain

$$\frac{\partial}{\partial \lambda} \Phi(\lambda) = 2a\lambda^3 + 3\lambda^2 - (a - 2)\lambda. \quad (13)$$

By using the theorem of differential calculus, we have

$$\begin{aligned} \frac{\partial}{\partial \lambda} \Phi(\lambda) &= \frac{\partial}{\partial \lambda} (\lambda^2) (ax + \lambda)_{x=\lambda^2} - \frac{\partial}{\partial \lambda} (\lambda) (ax + \lambda)_{x=\lambda} + \int_{\lambda}^{\lambda^2} dx \frac{\partial}{\partial \lambda} (ax + \lambda) \\ &= 2\lambda(a\lambda^2 + \lambda) - (a\lambda + \lambda) + \int_{\lambda}^{\lambda^2} dx \\ &= 2a\lambda^3 + 3\lambda^2 - (a - 2)\lambda. \end{aligned} \quad (14)$$

The result in Eq.(14) is equal to Eq. (13) which uses directly the partial differentiation of $\Phi(\lambda)$ with respect to λ .

Appendix C:

The Continuous Condition

In quantum mechanics, the wave function $\psi(x, t)$ means the probability amplitude of a particle located at x at time t . To interpret $\psi(x, t|\tau)$ as the probability amplitude for the particle at x to spend in $\Omega \equiv [a, b]$ prior to time t , a net time τ , we must require that $\psi(x, t|\tau)$ is square integrable both the x and τ ,

$$N(t) = \int dx \left| \int_0^t d\tau \psi(x, t|\tau) \right|^2. \quad (1)$$

The traversal wave function $\psi(x, t|\tau)$ means the probability amplitude of the particle located at x of having been in the region $\Omega \equiv [a, b]$ with net duration τ , prior to time t . We are to interpret $|\psi(x, t|\tau)|^2$ as a probability density for position measurement. So it implies strong constraints on $\psi(x, t|\tau)$:

1) $|\psi(x, t|\tau)|$ must tend to zero sufficiently and rapidly as $x \rightarrow \pm\infty$, so that the integral of $|\psi(x, t|\tau)|^2$ converges.

2) For a probability interpretation to be valid, we must also require that $\psi(x, t|\tau)$ is continuous in x and t , as a discontinuity of $\psi(x, t|\tau)$ would lead to ambiguous predictions for probabilities near the discontinuity.

3) $\psi(x, t|\tau)$ is a differentiable function in x and t . $\psi(x, t|\tau)$ satisfies the clocked SE

$$\left(-\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} + V(x) - i\hbar\Theta_{ab}[x] \frac{\partial}{\partial \tau} - i\hbar \frac{\partial}{\partial t} \right) \psi(x, t|\tau) = 0. \quad (2)$$

4) In the time-independent potential case, we may assume that $\frac{\partial}{\partial t} \psi(x, t|\tau)$ is continuous everywhere. If the potential energy is a smooth function, we may assume that $\frac{\partial}{\partial x} \psi(x, t|\tau)$ is continuous everywhere.

Appendix D:

Eliminating

the Apparatus Degree of Freedom

We define the SE for an observed particle, which contains the effects of the measurement, by eliminating the apparatus system using the identity

$$\frac{g}{2\pi\hbar} \int dp \frac{\langle \phi(p), t | \mathbf{H}_{total} - i\hbar \frac{\partial}{\partial t} | \Psi(t) \rangle}{\langle \phi(p), t | \phi(p), t \rangle} = 0. \quad (1)$$

We substitute the total state in Eq.(4.19) into Eq.(1)

$$\begin{aligned} & \frac{g}{2\pi\hbar} \int dp \frac{\langle \phi(p), t | \mathbf{H}_{total} - i\hbar \frac{\partial}{\partial t} | \Psi(t) \rangle}{\langle \phi(p), t | \phi(p), t \rangle} \\ &= \frac{g}{2\pi\hbar} \int dp \int dp' \frac{\langle \phi(p), t | \mathbf{H}_0 + \frac{\mathbf{p}^2}{2M} + g(t) \mathbf{P}(\Theta_{\mathbf{ab}}[\mathbf{x}] - \Lambda(t)) - i\hbar \frac{\partial}{\partial t} | \phi(p'), t \rangle \otimes |\psi_{p'}, \tau, t \rangle}{\langle \phi(p), t | \phi(p), t \rangle} \end{aligned} \quad (2)$$

where $|\psi_{p'}, \tau, t \rangle$ is given by

$$|\psi_{p'}, \tau, t \rangle = e^{\frac{i}{\hbar} g p' \tau} e^{-\left(\frac{i}{\hbar}\right) \int_0^t (\mathbf{H}_0 + g p' \Theta_{\mathbf{ab}}[\mathbf{x}]) dt'} |\psi_0 \rangle = e^{\frac{i}{\hbar} g p' \tau} |\psi_{p'}, t \rangle \quad (3)$$

and the variable τ is defined as

$$\tau = \int_0^t \Lambda(t') dt'. \quad (4)$$

We multiply $e^{\frac{i}{\hbar} g p' \tau}$ with the time evolution of the observed system, so the state of the apparatus in time is of the form

$$|\phi(p'), t \rangle = e^{-\frac{i}{\hbar} \frac{p'^2}{2M} t} |p' \rangle \langle p' | \phi_0 \rangle. \quad (5)$$

By differentiating on t ,

$$\frac{\partial}{\partial t} F(t, y(t)) = \frac{\partial}{\partial t} F(t, y) + \frac{\partial y(t)}{\partial t} \frac{\partial}{\partial y} F(t, y). \quad (6)$$

and

$$\frac{\partial \tau}{\partial t} = \Lambda(t) \quad (7)$$

we obtain

$$\begin{aligned} -i\hbar \frac{\partial}{\partial t} |\phi(p'), t\rangle \otimes |\psi_{p'}, \tau, t\rangle &= \frac{p'^2}{2M} |\phi(p'), t\rangle \otimes |\psi_{p'}, \tau, t\rangle - |\phi(p'), t\rangle \otimes i\hbar \frac{\partial}{\partial t} |\psi_{p'}, \tau, t\rangle \\ &= \frac{p'^2}{2M} |\phi(p'), t\rangle \otimes |\psi_{p'}, \tau, t\rangle \\ &\quad + gp' \Lambda(t) |\phi(p'), t\rangle \otimes |\psi_{p'}, \tau, t\rangle - |\phi(p'), t\rangle \otimes i\hbar \left(\frac{\partial}{\partial t} |\psi_{p'}, \tau, t\rangle \right)_\tau \end{aligned} \quad (8)$$

So Eq.(2) becomes

$$\begin{aligned} \frac{g}{2\pi\hbar} \int dp \frac{\langle \phi_0 | \phi_0 \rangle \left[\mathbf{H}_0 + gp'(\Theta_{ab}[x]) - i\hbar \left(\frac{\partial}{\partial t} \right)_\tau \right] |\psi_{p'}, \tau, t\rangle}{\langle \phi_0 | \phi_0 \rangle} &= 0 \\ \frac{g}{2\pi\hbar} \int dp \left[\mathbf{H}_0 + gp' \Theta_{ab}[x] - \left(i\hbar \frac{\partial}{\partial t} \right)_\tau \right] |\psi_{p'}, \tau, t\rangle &= 0 \\ \left\{ \mathbf{H}_0 - i\hbar \frac{\partial}{\partial \tau} \Theta_{ab}[x] - \left(i\hbar \frac{\partial}{\partial t} \right)_\tau \right\} |\psi, t | \tau\rangle &= 0. \end{aligned} \quad (9)$$

where $|\psi, t | \tau\rangle = \frac{g}{2\pi\hbar} \int dp e^{\frac{i}{\hbar} gp\tau} e^{-\left(\frac{i}{\hbar}\right) \int_0^t (\mathbf{H}_0 + gp\Theta_{ab}[x]) dt'} |\psi_0\rangle$ and the effective wave function can be written as

$$\begin{aligned} \psi(x, t | \tau) &= \frac{g}{2\pi\hbar} \int dp \langle x | \psi_{p'}, \tau, t\rangle \\ &= \frac{g}{2\pi\hbar} \int dp \langle x | e^{\frac{i}{\hbar} gp\tau} e^{-\left(\frac{i}{\hbar}\right) \int_0^t (\mathbf{H}_0 + gp\Theta_{ab}[x]) dt'} |\psi_0\rangle. \end{aligned} \quad (10)$$

Appendix E:

To Reduce the Total Propagator

The effective propagator which uses the relation

$$K_{eff}(x, x_0, t) = \frac{\int dy \int dy_0 K_{total} K_a^*}{\int dy \int dy_0 K_a K_a^*} \quad (1)$$

where $K_a(y, y_0; t) = \langle y | \exp\{-\frac{i}{\hbar} \int_0^t \mathbf{H}_A dt'\} | y_0 \rangle$ is the propagator of the pointer particle, in the form of a free particle propagator, $K_{total}(x, x_0; y, y_0; t) = \langle y | \otimes \langle x | U(t, t_0 = 0) | y_0 \rangle \otimes | x_0 \rangle$ is the propagator of the whole system. Straightforward substitution of the total propagator of Eq.(4.29) into Eq.(4.30) leads to

$$\begin{aligned} K_{eff}(x, x_0, t) &= \int dy \int dy_0 \langle y | \otimes \langle x | e^{-\frac{i}{\hbar} \int_0^t (\mathbf{H}_0 + \mathbf{H}_A + g\mathbf{P}(\Theta_{ab}[\mathbf{x}] - \Lambda(t')) dt')} | y_0 \rangle \\ &\quad \times \langle y_0 | e^{\frac{i}{\hbar} \int_0^t \mathbf{H}_A dt'} | y \rangle \otimes | x_0 \rangle \\ &\quad \times \left[\int dy \int dy_0 \langle y | \exp\{-\frac{i}{\hbar} \int_0^t \mathbf{H}_A dt'\} | y_0 \rangle \langle y_0 | \exp\{\frac{i}{\hbar} \int_0^t \mathbf{H}_A dt'\} | y \rangle \right]^{-1}. \end{aligned} \quad (2)$$

Using the completeness relation $I = \int dy_0 | y_0 \rangle \langle y_0 |$, Eq.(4.32) becomes

$$K_{eff}(x, x_0, t) = \int dy \langle y | \otimes \langle x | e^{-\frac{i}{\hbar} \int_0^t (\mathbf{H}_0 + g\mathbf{P}(\Theta_{ab}[\mathbf{x}] - \Lambda(t')) dt')} | y \rangle \otimes | x_0 \rangle \times \left[\int dy \langle y | y \rangle \right]^{-1}. \quad (3)$$

and inserting the completeness relation $I = \int dp | p \rangle \langle p |$ between $\langle y |$ and $| y \rangle$, leads to

$$\begin{aligned} K_{eff}(x, x_0, t) &= \int dy \int dp \langle y | p \rangle \langle p | \otimes \langle x | e^{-\frac{i}{\hbar} \int_0^t (\mathbf{H}_0 + g\mathbf{P}(\Theta_{ab}[\mathbf{x}] - \Lambda(t')) dt')} | y \rangle \otimes | x_0 \rangle \\ &\quad \times \left[\int dy \int dp \langle y | p \rangle \langle p | y \rangle \right]^{-1} \end{aligned}$$

$$\begin{aligned}
&= \int dy \int dp \langle p | \otimes \langle x | e^{\left[-\frac{i}{\hbar} \int_0^t (\mathbf{H}_0 + g p (\Theta_{ab}[\mathbf{x}] - \Lambda(t'))) dt'\right]} \otimes |x_0\rangle \\
&\quad \times \left[\int dy \int dp \right]^{-1} \\
&= \left(\frac{g}{2\pi\hbar} \right) \int dp \langle x | e^{\left[-\frac{i}{\hbar} \int_0^t (\mathbf{H}_0 + g p (\Theta_{ab}[\mathbf{x}] - \Lambda(t'))) dt'\right]} \otimes |x_0\rangle \times \left[\left(\frac{g}{2\pi\hbar} \right) \int dp \right]^{-1} \\
&= \int D[x] \delta(\tau - t_{ab}^{cl}[x]) e^{iS[x(t)]/\hbar} / \delta(0), \tag{4}
\end{aligned}$$

where $\delta(0) = \left(\frac{g}{2\pi\hbar} \right) \int dp$ is the normalization.

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